ON A CLASS OF DISTANCE-REGULAR GRAPHS

Ъy

MICHAEL A. GEORGIACODIS

Thesis Submitted for the Degree of Doctor of Philosophy at the University of London

Department of Mathematics Royal Holloway College University of London

October 1978



ProQuest Number: 10097469

All rights reserved

INFORMATION TO ALL USERS The quality of this reproduction is dependent upon the quality of the copy submitted.

In the unlikely event that the author did not send a complete manuscript and there are missing pages, these will be noted. Also, if material had to be removed, a note will indicate the deletion.



ProQuest 10097469

Published by ProQuest LLC(2016). Copyright of the Dissertation is held by the Author.

All rights reserved. This work is protected against unauthorized copying under Title 17, United States Code. Microform Edition © ProQuest LLC.

> ProQuest LLC 789 East Eisenhower Parkway P.O. Box 1346 Ann Arbor, MI 48106-1346

ON A CLASS OF DISTANCE-REGULAR GRAPHS

by ·

MICHAEL A. GEORGIACODIS

ABSTRACT

We prove that there is no distance-regular graph Γ having intersection array

$$i(\Gamma) = \left\{ \begin{array}{c} * & 1 & 1 & \dots & 1 & c \\ 0 & 0 & 0 & \dots & 0 & k-c \\ k & k-1 & k-1 & \dots & k-1 & * \end{array} \right\}, k > 2$$

with diameter d > 13.

ACKNOWLEDGEMENTS

I wish to express my deep gratitude to Dr. R.M. Damerell of Royal Holloway College under whose guidance and supervision this thesis was prepared. His helpful suggestions at every stage of this work were of the greatest value to me. I would also like to thank Professor H.G. Eggleston, Head of the Mathematics Department and all the staff for their kindness during the years of my studies at Royal Holloway College.

To my wife Aliki, I can only say you made it possible.

CONTENTS

	Page
INTRODUCTION	
Definitions and elementary results	l
Distance-regular graphs	3
CHAPTER ONE	
§1. The characteristic equation of B	12
§2. The multiplicity of λ as an eigenvalue	
of A	14
CHAPTER TWO	
<pre>§1. Preliminary results</pre>	20
§2. Factorization of $H_d(Y)$ over GF(2)	24
CHAPTER THREE	
§1. Case III $(r = s = 0)$	30
§2. Cases IV and V ($r > 2s \ge 0$) and $2s > r > 0$)	35
CHAPTER FOUR	
§1. Graphs of diameter $d = 2^t$ or $2^t + 1$	44
§2. Graphs of diameter $d = 2^{t} \times 3$ or $2^{t} \times 3 + 1$	49
§3. Necessary conditions for graphs of	
diameter $d = 2^{t} \times 5$ or $2^{t} \times 5 + 1$	53
§4. Graphs of diameter $d = 2^{t} \times 5$	57
§5. Graphs of diameter $d = 2^{t} \times 5 + 1$	60
CHAPTER FIVE	
<pre>\$1. Newton Polygons</pre>	62
§2. Proof of theorem 6	66
REFERENCES	69

•

Introduction

Definitions and elementary results

A <u>simple graph</u> Γ is a pair (V(Γ), E(Γ)) where V(Γ) is a set {v₁,v₂, ..., v_n} of distinct element called <u>vertices</u> and E(Γ) is a finite set of distinct unordered pairs of distinct elements of V(Γ) called edges.

Throughout this thesis the term graph will mean simple graph.

<u>Definition 1</u>. Two vertices v_i, v_j of a graph Γ are <u>adjacent</u> if $\{v_i, v_j\}$ is an edge.

Definition 2. A walk of length ℓ in Γ , joining v_i to v_j is a finite sequence of vertices of Γ

 $v_{i} = u_{0}, u_{1}, \dots, u_{\ell} = v_{j}$

such that u_t and u_{t+1} are adjacent for $0 \leq t \leq l-1$. A walk whose edges are all distinct is called a path.

Definition 3. A connected graph is a graph that contains a walk joining V_i, V_j for each pair v_i, v_j of vertices.

<u>Definition 4</u>. The <u>degree</u> of the vertex v_i is the number of edges having v_i as a vertex. A <u>regular</u> graph is a graph in which every vertex has the same degree. <u>Definition 5</u>. Let Γ be a graph whose vertex set is $V(\Gamma) = \{v_1, v_2, \dots, v_n\}$. The <u>adjacency matrix</u> of Γ is the $n \ge n$ matrix $A = A(\Gamma)$ whose entries a_{ij} are given by

 $a_{ij} = \begin{cases} 1, & \text{if } v_i & \text{and } v_j & \text{are adjacent} \\ 0, & \text{otherwise} \end{cases}$

Some elementary consequences of this definition are:

- 1. The eigenvalues of A are real.
- 2. The sum of the eigenvalues is zero.
- The sum of the entries in any row or column is equal to the degree of the corresponding vertex.
- 4. The number of walks of length ℓ in Γ joining v_{i} to v_{j} is the entry b_{ij} in A^{ℓ} . [5] p. 11

<u>Definition 6</u>. The <u>spectrum</u> of the graph Γ is the set of pairs

$$S = \{(\lambda_0, m(\lambda_0)), (\lambda_1, m(\lambda_1)), \dots, (\lambda_u, m(\lambda_u))\}$$

where λ_i , i = 0,1, ..., v are the distinct eigenvalues of the matrix A and m(λ_i) their multiplicities.

Proposition 1 [5] p.14 If Γ is a regular connected graph
of degree k then

- (1) k is a simple eigenvalue
- (2) For any eigenvalue λ of A(Γ), we have $|\lambda| \leq k$.

<u>Definition 7</u>. The number of edges in α shortest walk joining v_i to v_j is called the <u>distance</u> in Γ between v_i and v_j and is denoted by $\delta(v_i, v_j)$.

The diameter $d(\Gamma) = d$ of a graph Γ is the maximum of the distances i.e.

$$d = \max \qquad \delta (v_i, v_j)$$
$$v_i, v_j \in V(\Gamma)$$

Definition 8. The adjacency algebra of a graph is the algebra of polynomials, over the complex field, in the adjacency matrix A.

<u>Proposition 2</u> [5] A connected graph Γ with n vertices and diameter d has at least d+l and at most n distinct eigenvalues.

Distance-Regular Graphs.

Let Γ be a connected graph of diameter d. Then, for any vertex v, the vertex set V(Γ) can be partitioned into disjoint subsets

 $\Gamma_0(\mathbf{v}), \Gamma_1(\mathbf{v}), \ldots, \Gamma_d(\mathbf{v}), \text{ where }$

 $\Gamma_{f}(v) = \{u \in V(\Gamma) | \delta(u,v) = f\}, f = 0,1,...,d$.

Graphs of small diameter can be drawn by arranging their vertices in rows according to distance from an arbitrary vertex v. For example the graph of figure 2 is the same as the one in figure 1 but drawn in the manner just described.









For any connected graph Γ , and any vertices u,v of Γ , let $S_{h,i}(u,v) = |\{w \in V(\Gamma) | \delta(u,w) = h \text{ and } \delta(v,w) = i\}|;$ that is, $S_{hi}(u,v)$ is the number of vertices of Γ whose distance from u is h and whose distance from v is i.

<u>Definition 9</u>. The connected graph Γ with diameter d is <u>distance-h-regular</u> if for all integers i and j $(0 \leq i, j \leq d)$ and for all pairs of vertices u,v with $\delta(u,v) = j$ the number

$$S_{hi}(u,v) = S_{hij}$$
 (say)

depends only on h,i,j and not on the individual pair (u,v). Γ is <u>distance-regular</u> if it is distance-h-regular for all h, $0 \leq h \leq d$. Theorem I [6] If Γ is distance-l-regular then Γ is distance-regular.

For a proof see [6].

For a fixed j, the number S_{lij} counts the vertices w such that w is adjacent to u and $\delta(v,w) = i$, where $\delta(u,v) = j$. Now, if w is adjacent to u and $\delta(u,v) = j$, then $\delta(v,w)$ must be one of the numbers j-1, j, j+1; in other words

We introduce the notation

where $0 \leq j \leq d$, except that c_0 and b_d are undefined. Then for any arbitrary vertex $v \in V(\Gamma)$ and a vertex $u \in \Gamma_j(v)$ we have that u is adjacent to c_j vertices in $\Gamma_{j-1}(v)$, a_j vertices in $\Gamma_j(v)$ and b_j vertices in $\Gamma_{j+1}(v)$.

<u>Definition 10</u>. The <u>intersection array</u> of a distance-regular graph is the array

 $I(\Gamma) = \begin{cases} * & c_1 \cdots & c_j \cdots & c_d \\ a_0 & a_1 \cdots & a_j \cdots & a_d \\ b_0 & b_1 \cdots & b_j \cdots & * \end{cases}$ o.1

Now let Γ be a distance regular-graph of diameter d and vertex set $V(\Gamma) = \{v_1, \dots, v_n\}$ and let $A_i, 0 \leq i \leq d$ be the n x n matrix whose entries are

$$a_{rs} = \begin{cases} 1, & \text{if } \delta(v_r, v_s) = i \\ 0, & \text{otherwise} \end{cases}$$

For those matrices we observe that $A_0 = I$, $A_1 = A(\Gamma)$ (The usual adjacency matrix) and $A_0 + A_1 + \dots + A_d = J$ (J being the matrix whose all the entries are equal to 1).

Theorem II $\begin{bmatrix} 5 \end{bmatrix}_{p.136}$. Let Γ be a distance-regular graph of diameter d. Then $\{A_0, A_1, \dots, A_d\}$ is a basis, for the adjacency algebra of the graph, described by the formula

$$A_{h}A_{i} = \sum_{j=0}^{d} S_{hij}A_{j}$$

Proposition 3 [5] ρ Wilf Γ is a distance-regular graph of degree k and diameter d, then A(Γ) has d+1 distinct eigenvalues $k = \lambda_0, \lambda_1, \dots, \lambda_d$ which are the eigenvalues of the (d+1) x (d+1) matrix B whose, entries are (B)_{ij} = S_{iij}, i,j ϵ {0,1,...,d}.

Notice that B is a tridiagonal matrix with entries

°j'	when	j-l = i	in the upper diagonal]	
^a j,	when	j = i	in the main diagonal	ł	0.2
^b ;'	when	j+l = i	in the lower diagonal.		

6

<u>Definition 11</u>. The matrix B is called the <u>intersection</u> <u>matrix</u> of Γ .

<u>Theorem III</u> [5] μ .143. Let Γ be a distance-regular graph with intersection matrix B, and suppose that u_i, v_i are left and right eigenvectors such that $(u_i)_0 = (v_i)_0 = 1$ corresponding to the eigenvalue λ_i of B. Then

$$m(\lambda_{i}) = \frac{N}{\frac{d}{\Sigma} k_{j}(u_{i})_{j}^{2}}, \quad 0 \leq i \leq d$$

$$i=0$$

where N is the number of vertices.

The natural question to be asked is when an arbitrarily given array corresponds to a distance-regular graph?

The answer to this question is not yet known but the following theorem yields certain conditions which although not sufficient for the existence of the graph, related to a given array, they are nevertheless so restrictive that most known arrays satisfying these conditions correspond to a graph.

Theorem IV $[5]_{p.144}$ If the array (0.1) is the intersection array of a distance-regular graph of diameter d then 1. $a_0 = 0$, $b_0 = k$ (the degree of the graph), $c_1 = 1$ and $k = a_i + b_i + c_i$ for $1 \le i \le d-1$ $k = a_d + c_d$.

2. For
$$2 \leq i \leq d$$
 the numbers
 $k_i = (k \ b_1 \ \cdots \ b_{i-1})/(c_2 c_3 \ \cdots c_i)$ are integers.
3. $k \geq b_1 \geq \cdots \geq b_{d-1}$; $1 \leq c_2 \leq \cdots \leq c_d$.

4. If
$$N = 1 + k + k_2 + \dots + k_d$$
 $1 \le i \le d-1$ then
N.k = O(mod 2) and $k_i d_i = O(mod 2)$.

5. For each eigenvalue
$$\lambda_i$$
 of the matrix B, given by (0.2) with eigenvector u_i defined as in theorem III the number $\frac{N}{\sum_{j=0}^{d} k_i(u_i)_j^2}$, is an integer.

<u>Definition 12</u> An array of the form of (0.1) is said to be <u>feasible</u> if it satisfies the conditions of theorem IV.

In [16] Tutte showed that the number of vertices N, say, of a regular graph whose degree (k \geq 3) and girth ($\gamma \geq$ 3) are given is greater than or equal to

 $1 + k + k(k-1) + ... + k(k-1)^{\frac{1}{2}(\gamma-3)}$ if γ is odd

 $1 + k + k(k-1) + ... + k(k-1)^{\frac{1}{2}\gamma-2} + (k-1)^{\frac{1}{2}\gamma-1}$ if γ is even

Here the <u>girth</u> of a graph is the length of one of its shortest circuits.

and

0.3

A graph which attains the bound (0.3) is called a <u>Moore graph</u> if γ is odd and a <u>Generalized Polygon</u> if γ is even.

A lot of work has been done on the classification of such graphs. Generalized Polygons have been studied by Feit and Higman [9], Singleton [15] and Benson [3]. Moore graphs have been studied by Hoffman and Singleton [12], Vijayan [17], Bannai and Ito [1] and Damerell [6].

In his book [5] ch23Biggs considered both types of graphs as special cases of the distance-regular graph of diameter d whose intersection array is

	*	1	l	• • •	1	С		
ł	0	0	0	• • •	0	k-c	>, k > 2	0.4
	k	k-l	k-l		k-1	*		

The case c = k is a Generalized Polygon and the case c = 1 is a Moore graph.

In this thesis we investigate the feasibility of the intersection array (0.4) using the methods and formulae given by Biggs [5] and we prove that this is not feasible if d > 13.

Supposing that a graph of this type exists, Biggs has derived a formula for the minimum polynomial of its adjacency matrix A.

In chapter one, by using that formula we calculate the

multiplicity of each eigenvalue λ of the matrix A as a function of λ . Using that result (Theorem 1 below) Bannai and Ito [2] have proved that the characteristic polynomial splits into linear or quadratic factors.

In chapter two we prove that the characteristic polynomial splits into quadratic factors over GF(2) only if its degree (= d) is of the form $d = 2^{t} \times f$ or $2^{t} \times f + 1$ where f = 1,3 or 5. To get this result since the characteristic polynomial $G_{d}(x)$ alone does not always provide the answer, we construct another polynomial $H_{d}(Y)$ whose roots are linear or quadratic over the rationals whenever the roots of the characteristic polynomial are.

In chapter three the factorization of $G_d(x)$ and $H_d(Y)$ over GF(2), provides the information that the constant terms of these polynomials are divisible by a certain power of 2. But we observe that this happens only when $t \leq 4$. From this it follows that $d \leq 81$.

In chapter four we classify our graphs according to the value of f. When f = 1 the polynomial $H_d(Y)$, reduced modulo $Y^2 - 4Y$, provides the information that t < 4. In the case f = 3 the value of the polynomial $H_d(Y)$ at Y = θ , where θ is any odd numbers, provides a necessary condition which enables us to eliminate t = 4.

When f = 5, the same polynomial, reduced modulo $Y^2 + \theta Y + \theta$ yields the conditions which prevent t from being 3 or 4. From these results we get that $d \leq 25$. 10

Chapter five deals with graphs of diameters 25 and 24. There from the theorem of Dumas [7] we derive the conditions which forbid those diameters.

In conclusion I wish to state that the principal result contained in this thesis, which is described in the abstract, was obtained by my own research.

CHAPTER ONE

Eigenvalues and their multiplicities

We adopt the notation of Biggs [5] which is h = k-1, $q = +\sqrt{k-1}$, $\lambda = 2q \cos \alpha$ and we regard the matrix

	0	l			·					
	k	0	1							
		k-1	0	•						
B =		•	k-l	•	•					1.2
				• '	•	•				
					•	•	l ·		·	
						,	0	с	ŀ	•
							k-l	k-c		
,										,

as the intersection matrix of a D-R graph. Then the characteristic equation of B is given by the following result. ([5] lemma 23.3). The number λ is an eigenvalue of the matrix B if either

 $\lambda = k$ 1.3

or

 $\lambda = + 2q \cos \alpha$

and

F(cosar)=0 where F is defined by

 $q \frac{\sin(d+1)\alpha}{\sin\alpha} + c \frac{\sin d\alpha}{\sin\alpha} + \frac{c-1}{q} \frac{\sin(d-1)\alpha}{\sin\alpha} \equiv F_d(\cos\alpha) \qquad 1.5$

where d is the diameter of the putative graph.

1.1

1.4

In this chapter in §1 we calculate the recursion for $F_d(\cos\alpha)$ and we exclude $\lambda = -2q$ from being an eigenvalue. In §2 we express the multiplicity $m(\lambda)$ say of any eigenvalue λ of the adjacency matrix A of the assumed D-R graph as a function in λ . Finally we state the theorem of Bannai and Ito which is the starting point of our investigation.

\$1. The characteristic equation of B.

Lemma 1.1. With F, as defined in (1.5)

$$F_1 = 2q\cos \alpha + c$$
, $F_2 = 4q \cos^2 \alpha + 2c \cos \alpha + \frac{c-1}{q} - q$ 1.6

$$F_d = 2 \cos \alpha F_{d-1} - F_{d-2}, d > 2$$
 . 1.7

Proof. The Tchebycev polynomials of the second kind are of the form
([8] (10.11.12))

$$U_{\eta}(\cos\alpha) = \frac{\sin(n+1)\alpha}{\sin\alpha}$$
 1.8

and satisfy the following recurrence relation ([8]. (10.11.16))

$$U_{\eta+1}(\cos\alpha) = 2 \cos\alpha U_{\eta}(\cos\alpha) - U_{\eta-1}(\cos\alpha)$$
 1.9

Hence from 1.5 we get

$$F_{d}(\cos\alpha) = q U_{d}(\cos\alpha) + c U_{d-1}(\cos\alpha) + \frac{c-1}{q} U_{d-2}(\cos\alpha) \cdot 1.10$$

Thus

 $F_{d}(\cos \alpha) = q\{2 \cos \alpha U_{d-1} - U_{d-2}\} + c\{2 \cos \alpha U_{d-2} - U_{d-3}\}$

$$+ \frac{c-1}{q} \{ 2 \cos \alpha \ U_{d-3} - U_{d-4} \}$$
 1.11

=
$$2 \cos \alpha F_{d-1} - F_{d-2}$$
 . 1.12

Now putting d = 1,2 into 1.5 we get 1.6.

We note for future use the formula

$$F_{d}(\cos \alpha) = (2q \cos \alpha + c) U_{d-1}(\cos \alpha) + \frac{c-1-q^2}{q} U_{d-2}(\cos \alpha)$$
 1.13

got by substituting for U_d (cosa) in 1.10.

<u>Proposition 1.1</u>. $\lambda = -2q$ is never an eigenvalue. <u>Proof</u>. Let q be irrational. Then if -2q is an eigenvalue so is +2q. But $\lambda = +2q$ implies $\alpha = 0$ by 1.1 and in that case 1.5 gives, after using L'Hôpital's rule that

$$q(d+1) + cd + \frac{c-1}{q} (d-1) = 0$$
 1.14

which is impossible since this is strictly positive. Therefore q has to be rational and integral. Now if the integer $\lambda = -2q$ is an eigenvalue then $\alpha = \pi$ and again by L'Hôpital's rule from 1.5 we get

$$(-1)^{d-1} \{q(d+1) - cd + \frac{c-1}{q} (d-1)\} = 0$$
 1.15

$$c-1 = \frac{-dq^{2} + dq - q^{2}}{-dq + d - 1} = q + \frac{q^{2} - q}{dq - d + 1}$$
1.16

 $\frac{q^2 - q}{dq - d + 1}$ has to be an integer

$$\frac{q}{dq - d + 1} = q - \frac{d(q^2 - q)}{dq - d + 1}$$
 must be an integer

... dq - d + l <u>≤</u> q

which is not true when q > 1.

Now if q = 1 then k = 2 by 1.1, in which case our graph is a polygon with 2d + 1 edges. 1.17

§2. The multiplicity of λ as an eigenvalue of A.

Theorem 1. Let λ be an eigenvalue of the intersection matrix B and m(λ) its multiplicity, as an eigenvalue of the adjacency matrix A. Then

$$\frac{N}{m(\lambda)} = \frac{\lambda - h - 1}{(h+1)(\lambda^2 - 4h)} \left[\frac{(h+1-c)(\lambda c + 2h + 2c - 2)}{\lambda(c-1) + h + (c-1)^2} + 2d(\lambda + h + 1) \right] \equiv \Sigma(\lambda)$$
 1.18

(say) where N is the number of vertices of the supposed graph. <u>Proof.</u> By [5] p.158 the multiplicity of λ as an eigenvalue of the matrix A is given by

$$\frac{N}{m(\lambda)} = \Sigma(\lambda) = \sum_{i=0}^{d} k_i u_i^2$$
1.19

where

$$k_0 = 1$$
, $k_i = kh^{i-1}$, $(1 \le i < d)$, $k_d = c^{-1}kh^{d-1}$ 1.20

and $\underline{u} = (u_{\vec{0}} \cdot 1, u_{1}, \dots, u_{d})$ is a left eigenvector of B corresponding to the eigenvalue λ . Now since the first d columns of B are the same as in the matrix B of [6], the formulae derived there for \underline{u} in terms of any eigenvalue λ hold.

Thus

$$u_{i} = C\left(\frac{\theta}{q}\right)^{i} + D\left(\frac{\theta^{-1}}{q}\right)^{i} \qquad 1.21$$

where
$$C = \frac{h\theta - \theta^{-1}}{k(\theta - \theta^{-1})}$$
, $D = \frac{h\theta^{-1} - \theta}{k(\theta^{-1} - \theta)}$ and $\theta = e^{i\alpha}$. 1.22

To simplify the resulting algebra we adopt the convention that if W is a rational function of θ , then W is the function got by replacing θ by θ^{-1} throughout. Thus

$$k_0 u_0^2 = 1 = h^{-1} + kh^{-1} (C^2 + 2CC + C^2)$$
 1.23

$$k_{i} u_{i}^{2} = kh^{-1} (C^{2} \theta^{2i} + 2CC + C^{2} \theta^{-2i}), 1 \le i < d$$
 1.24

and

$$k_{d} u_{d}^{2} = c^{-1} k h^{-1} (c^{2} \theta^{2d} + 2c\hat{c} + \hat{c}^{2} \theta^{-2d})$$
 . 1.25

Hence

$$\Sigma(\lambda) = \sum_{i=0}^{d} k_{i} u_{i}^{2} = -h^{-1} + k h^{-1} c^{-1} \{Z + Y + \widehat{Z}\}$$
1.26

where

$$Y = 2CC (dc + 1)$$
 1.27

and

$$Z = C^{2} \{ c \sum_{i=0}^{a} \theta^{2i} + (1-c) \theta^{2d} \}$$
 1.28

Consider Z. Sum the series and multiply by $k^2(q\theta + c-1) \cdot (\theta-1)^3$. Then

Now if we put $\theta = e^{i\alpha}$ we have

$$\sin n\alpha = \frac{e^{in\alpha} - e^{in\alpha}}{2i} = \frac{\theta^n - \theta^{-n}}{2i}$$
 1.30

and equation 1.5 becomes

$$\theta^{2d}$$
 (q0 + c - 1)(q0 + 1) = (q + 0) [q + (c-1)0] 1.31

and substituting for θ^{2d} into 1.29 we get

$$k^{2}(\theta^{2}-1)^{2} (q\theta+c-1). Z = (h\theta^{2}-1)(q\theta-1) [(c-1)\theta^{2}+qc\theta+(c-1)(c-q^{2})]$$
 1.32

Then multiplying both sides of the above equation by $\theta^{-2}(q\theta^{-1} + c - 1)$ and arranging the R.H.S. terms in powers of θ we get

$$A.Z = \theta^{3}hq(c-1)^{2} + \theta^{2}.h(c-1) [h(c+1) - (c-1)]$$

$$+ \theta q[h^{2}(3c-c^{2}-1) + h(c-1)(c^{2}-2c-1) - (c-1)^{2}]$$

$$- h^{3}(c-1) + h^{2}(2c^{2}-4c+1) - h(c-1)(c^{2}+1) + (c-1)^{2}$$

$$+ \theta^{-1}q[h^{2}(c-1) - h(2c-1) + (c-1)(-c^{2}+2c+1)]$$

$$+ \theta^{-2}[h^{2}(c-1) - h(2c^{2}-4c+1) + c(c-1)^{2}] + \theta^{-3}q(c-1)(c-h)$$
1.33

where

$$A = k^{2}(\theta^{2}-1)^{2} (q\theta+c-1)(q\theta^{-1}+c-1).\theta^{-2}$$

= $k^{2}(\theta-\theta^{-1})^{2} [q(c-1)(\theta+\theta^{-1}) + h + (c-1)^{2}] = \hat{A}$. 1.34

Thus

$$A(Z + \hat{Z}) = (\theta^{3} + \theta^{-3}), q(c-1) [h(c-2) + c]$$

+ $(\theta^{2} + \theta^{-2}) [h^{2}(c^{2}+c-2) - h(3c^{2}-6c+2) + c(c-1)^{2}]$
+ $(\theta+\theta^{-1}), q[h^{2}(4c-c^{2}-2) + h(c-1)(c^{2}-2c-2) - hc + (c^{2}-1)(2-c)]$
- $2h^{3}(c-1) + 2h^{2}(2c^{2}-4c+1) - 2h(c-1)(c^{2}+1) + 2(c-1)^{2}$. 1.35

Now $\theta = e^{i\alpha}$ thus $\theta + \theta^{-1} = \frac{\lambda}{q}$, $\theta^2 + \theta^{-2} = \frac{\lambda^2 - 2h}{h}$, $\theta^3 + \theta^{-3} = \frac{\lambda(\lambda^2 - 3h)}{q^3}$ and $(\theta - \theta^{-1})^2 = \frac{\lambda^2 - 4h}{h}$. From which we get that

$$A = k^{2} (\lambda^{2} - 4h) [\lambda \cdot (c-1) + h + (c-1)^{2}] \cdot \tilde{h}^{-1}$$
1.37

and

$$A(Z + \widehat{Z}) \cdot h = \lambda^{3}(c-1) [h(c-2) + c] + \lambda^{2}[h^{2}(c^{2}+c-2) - h(3c^{2}-6c+2) + c(c-1)^{2}] + \lambda \cdot h[h^{2}(-c^{2}+4c-2) + h(c-1)(c^{2}-5c+4) - hc + (c-1)(2-2c-c^{2})] - 2h [h^{3}(c-1) - h^{2}(c^{2}-5c+3) - h(-c^{3}+4c^{2}-7c+3) + (c-1)^{3}] . 1.38$$

Similarly by equation 1.27 we get

$$Y = 2C\hat{C}(dc+1) = \frac{h^2 + 1 - h(\theta^2 + \theta^{-2})}{k^2 [2 - (\theta^2 + \theta^{-2})]} \cdot 2(dc+1)$$
$$= \frac{(h+1)^2 - \lambda^2}{k^2 (4h - \lambda^2)} \quad h.2(dc+1) \quad . \qquad 1.39$$

Thus

$$h AY = [\lambda^2 - (h+1)^2] [\lambda.(c-1) + h + (c-1)^2].2h(dc+1)$$
 . 1.40

Now equation 1.26 can be written in the form

hc A
$$\Sigma(\lambda)$$
 = - cA + kA{Z+Y+Z} 1.41

$$= (h+1).c.h\{\lambda^{3}(c-1).2d + \lambda^{2} [h(c+2d) - c(c-1) + 2d(c-1)^{2}]\}$$

$$+ (h+1).c.h \cdot \lambda\{h^{2}[2-c-2d (c-1)] + h[c^{2}-2c-4d (c-1)] + (c-1) (2-c-2d)\}$$

$$+ 2h(h+1).c \{-h^{3}(d+1) - h^{2} [d(c^{2}-2c+3) + 1] - h[d(2c^{2}-4c+3) - (c-1)^{2}]$$

$$+ (c-1)^{2} (1-d)\} \cdot 1.42$$

Hence

(h+1)
$$(\lambda^2 - 4h) [\lambda(c-1) + (c-1)^2 + h]. \Sigma(\lambda) =$$

 $[\lambda - (h+1)] \{(h+1-c)[c\lambda+2(h+c-1)] + 2d(\lambda+h+1)[(c-1)\lambda + (c-1)^2 + h]\}. 1.43$ From which we get 1.18. Theorem 1 shows that the multiplicity $m(\lambda)$ of each eigenvalue of the incidence matrix A is a quotient of two cubic polynomials in λ . This together with the fact that the multiplicity $m(\lambda)$ has to be rational implies that all the eigenvalues of the assumed D-R graph must be of degree ≤ 3 over the rationals.

This result has been improved by Bannai and Ito. In [2] they prove the following .

Theorem 2. If Γ is a D-R graph with intersection matrix B and valency k > 2, then the roots of the characteristic polynomial of B are all of degree ≤ 2 over the rationals.

For proof see [2] theorem A.

CHAPTER TWO

The factorization of the characteristic polynomial of the matrix B over GF(2).

If a D-R graph with intersection matrix B exists, then, from the theorem of Bannai and Ito, we know that the roots of its characteristic polynomial will be all of degree less than or equal t9 2, over the rationals. Consequently, if we reduce that polynomial modulo 2, this must have all its roots in GF(4).

Definition 2.1. Let

$$G(\mathbf{x}) = q^{d-1} F_{d}(\cos \alpha) \qquad 2.1$$

where

$$\dot{x} = 2q \cos \alpha$$
 2.2

and $F_{d}(\cos\alpha)$ is here regarded as a polynomial in $\cos\alpha$.

By lemma 1.1 the polynomial $G_d(x)$ satisfies the following recurrence relation.

$$G_{d}(x) = xG_{d-1}(x) - hG_{d-2}(x), \quad d > 2$$
 2.3

where

 $G_1(x) = x + c$, $G_2(x) = x^2 + cx + c - k$. 2.4

The polynomial $(x-k) G_d(x)$ is monic and of degree d + 1. Its roots are those given by [5] lemma 23.3. Thus $(x-k)G_d(x)$ is the characteristic polynomial of the matrix B. Therefore if the graph exists, $G_d(x)$, reduced modulo 2, will have all its roots in GF(4).

Now when h is odd this is not always possible. But when h is even the polynomial $G_d(x)$ factorizes trivially over GF(2).

To overcome this difficulty we construct another polynomial in a new variable Y, whose roots have to be rational or quadratic whenever the roots of $G_d(x)$ are. Moreover, this new polynomial reduced modulo 2, has all its roots in GF(4) only when certain conditions for d are satisfied.

The main result of this chapter is <u>Theorem 3</u>. If a D-R graph with intersection matrix B exists then its diameter has to be of the form

 $d = 2^{t} x f$ or $2^{t} x f + 1$, where f = 1 or 3 or 5.

Preliminary results

Definition 2.2. Let

$$H_{d}(Y) = (-1)^{d} h F_{d}(\cos \alpha) F_{d}(-\cos \alpha)$$
 2.5

where

$$Y = \frac{x^2}{h} = 4 \cos^2 \alpha = 2 \cos 2\alpha + 2.$$
 2.6

The so defined H(Y) is a polynomial in Y of degree d. The degree of each root of H(Y), over the rationals, is less than or equal to the degree of the corresponding eigenvalue x of the intersection matrix B.

Now since

$$F_d(-\cos\alpha) = F_d(\cos\beta)$$
 where $\beta = \pi - \alpha$ 2.7

and since

$$\frac{\sin n\beta}{\sin\beta} = (-1)^{n+1} \frac{\sin n\alpha}{\sin\alpha}$$
2.8

we get that

$$H_{d}(Y) = h\left[\left[q\frac{\sin(d+1)\alpha}{\sin\alpha} + \frac{c-1}{q} \frac{\sin(d-1)\alpha}{\sin\alpha}\right]^{2} - c^{2} \frac{\sin^{2}d\alpha}{\sin^{2}\alpha}\right] \qquad 2.9$$

Putting
$$q^2 = h$$
 we get
 $4 \sin^2 \alpha H_d(Y) = -2(c-1)^2 \cos 2(d-1)\alpha + 2h(c^2-2c+2) \cos 2d\alpha$
 $- 2h^2 \cos 2(d+1)\alpha + 2h^2 + 2(c-1)^2 - 2hc^2 + 4h(c-1) \cos 2\alpha$ 2.10

Definition 2.3 Define

$$K_{d}(Y) = -2(c-1)^{2}\cos 2(d-1)\alpha + 2h(c^{2}-2c+2)\cos 2d\alpha - 2h^{2}\cos 2(d+1)\alpha$$
 2.11

$$M(Y) = 2h^{2} + 2(c-1)^{2} - 2hc^{2} + 4h(c-1) \cos 2\alpha$$
$$= 2[h(c-1)Y + (h-c+1)^{2} - hc^{2}]$$
2.12

Then

$$(4-Y) H_{d}(Y) = K_{d}(Y) + M(Y)$$
 . 2.13

Lemma 2.1

$$K_{o}(Y) = -\{h^{2} + (c-1)^{2}\}Y + 2\{(h-c+1)^{2} + hc^{2}\}$$
 2.14

$$K_{1}(Y) = -h^{2}Y^{2} + h\{c^{2}-2(c-1) + 4h\}Y - 2\{(h-c+1)^{2} + hc^{2}\}$$
 2.15

$$K_{d}(Y) = (Y-2) K_{d-1}(Y) - K_{d-2}(Y)$$
 . 2.16

<u>Proof</u> The polynomials $\cos \eta \theta = T_{\eta}(\cos \theta)$ are the Tchebycev polynomials of the first kind and satisfy the following recurrence relation [[8], (10.11.16)].

$$T_{\eta+1}(\cos\theta) = 2\cos\theta T_{\eta}(\cos\theta) - T_{\eta-1}(\cos\theta) . \qquad 2.17$$

Now if we put $\theta = 2\alpha$ 2.11 can be written on the form

$$K_{d}(Y) = -2(c-1)^{2} T_{d-1} + 2h(c^{2}-2c+2) T_{d} - 2h^{2} T_{d+1}$$
 2.18

Hence by 2.17

$$K_{d}(Y) = 2\cos 2\alpha \left[-2(c-1)^{2} T_{d-2} + 2h(c^{2}-2c+2) T_{d-1} - 2h^{2} T_{d}\right]$$

- $\left[-2(c-1)^{2} T_{d-3} + 2h(c^{2}-2c+2) T_{d-2} - 2h^{2} T_{d-1}\right]$
= $2\cos 2\alpha K_{d-1}(Y) - K_{d-2}(Y)$. 2.19

Thus from 2.6 we get 2.16. Next putting d = 0,1 into 2.11 we get 2.14, 215.

Corollary 2.1.
$$H_d(Y) = (Y-2) H_{d-1}(Y) - H_{d-2}(Y) + M(Y)$$
 2.20

$$H_{o}(Y) = (k-c)^{2}$$
, $H_{1}(Y) = h^{2}Y - hc^{2}$. 2.21

Proof.	From	2.13	`

$$K_{d}(Y) = (4-Y) H_{d}(Y) - M(Y), d = 0,1, \dots$$
 2.22

Thus for $d \geq 2$ 2.16 becomes

 $(4-Y) H_{d}(Y) - M(Y) = (4-Y) [(Y-2) H_{d-1}(Y) - H_{d-2}(Y)] + (3-Y) M(Y)$ from which we get 2.20.

Now if we put d = 0,1 into 2.9 we get the stated values of $H_0(Y)$, $H_1(Y)$.

<u>Definition 2.4</u> Put c-l = e. Then we define r,s such that $2^{r} \parallel h$ and $2^{s} \parallel e$. Also define p = min(r,2s) and $L_{d}(Y) = 2^{-p} H_{d}(Y)$. Denote reduction modulo 2 by an asterisk. I. $L_d(Y)$ has all its coefficients integral and $2^{-p} M(Y) \equiv O(mod 2)$.

II. Let ρ,σ be the roots of the equation

$$\rho^2 + Y\rho + 1 = 0$$
 2.23

in characteristic 2. Then $\rho = \sigma^{-1}$ and $\rho L_1^* + L_0^* + L_0^{-1} + \rho^2 L_0^* + \rho^2$

$$L_{d}^{*}(Y) = \frac{\rho L_{1}^{*} + L_{0}^{*}}{\rho^{2} + 1} \cdot \rho^{d} + \frac{\rho^{2} L_{0}^{*} + \rho L_{1}^{*}}{\rho^{2} + 1} \cdot \sigma^{d} \qquad 2.24$$

Proof By (2.12) and (2.21)
$$\frac{1}{2}M(Y) = h e Y + (h-e)^2 - h(e+1)^2$$

 $H_0(Y) = (h - e)^2$, $H_1(Y) = h^2Y - h(e+1)^2$. By inspection we
see that each term of $H_0(Y)$ or $H_1(Y)$ or $\frac{1}{2}M(Y)$ is divisible
by h or e and hence by 2^p .

II. From 2.20 and the definition of $L_d(Y)$ we have

$$L_{d}(Y) = (Y-2) L_{d-1}(Y) - L_{d-2}(Y) + 2^{-p}M(Y), d \ge 2$$
. 2.25

Reducing modulo 2 we get

$$L_{d}^{*}(Y) = Y L_{d-1}^{*}(Y) - L_{d-2}^{*}(Y), \quad d \ge 2.26$$

Now the solution to 2.26 is

$$L_{d}^{*} = A\rho^{d} + B\sigma^{d}$$
 2.27

where ρ,σ are the roots of the equation 2.23 and A,B the solution of the system

$$A + B = L_0^*$$

$$A\rho + B\sigma = L_1^*$$

$$2.28$$

from which we get 2.24.

Factorization of $H_d(Y)$ over GF(2). §2.

We next consider how the polynomial $L_{d}^{*}(Y)$ factorizes in To do that we first write 2.21 in the form GF(2) .

$$H_0(Y) = (h - e)^2$$
, $H_1(Y) = h^2 - h(e + 1)^2$ 2.29

and separate the following five cases.

2s > r = 0I. II. 2s = r > 0III. 2s = r = 0IV. 2s > r > 0V. $r > 2s \ge 0$

where r,s are as in definition 2.4 .

If $\rho\,,\sigma$ are the roots of the equation Lemma 2.3.

$$p^2 + Y_p + 1 = 0$$
 2.30

III

v

in characteristic 2, then

$$\begin{bmatrix} \frac{1}{(\rho+1)\rho^{d}} & (\rho^{2d+1}+1) & \text{in case I} \\ \frac{1}{(\rho+1)\rho^{d-1}} & (\rho^{2d-1}+1) & \text{II} \end{bmatrix}$$

$$L_{d}^{*}(Y) = \begin{cases} \frac{1}{\rho^{d}} (\rho^{d} + 1)^{2} & \text{III} \\ \frac{1}{(\rho^{2} + 1)\rho^{d-1}} (\rho^{d} + 1)^{2} & \text{IV} \end{cases}$$

$$\frac{1}{(\rho^2+1)\rho^{d-2}} (\rho^{d-1}+1)^2$$

2.30^b

$$\frac{Proof}{L_0} = 2^{-p} (h-e)^2$$

$$L_1 = 2^{-p} [h^2Y - h(e+1)^2]$$
2.31

.

.

Case I.
$$L_0^* \equiv h^2 \equiv 1$$
 (mod 2)
 $L_1^* \equiv (h^2 \Upsilon - h.1) \equiv \Upsilon + 1 = \rho + \sigma + 1$

and 2.24 becomes

$$L_{d}^{*} = \frac{\rho(\rho + \rho^{-1} + 1) + 1}{\rho^{2} + 1} \rho^{d} + \frac{\rho^{2} + \rho(\rho + \rho^{-1} + 1)}{\rho^{2} + 1} \rho^{-d}$$

$$= \frac{\rho^{2} + \rho}{\rho^{2} + 1} \rho^{d} + \frac{\rho + 1}{\rho^{2} + 1} \rho^{-d}$$

=
$$\frac{1}{(\rho+1)\rho^d} \cdot (\rho^{2d+1} + 1)$$

Case II.
$$L_{0}^{*} \equiv 2^{-2s} e^{2} \equiv 1$$
 (mod 2)
 $L_{1}^{*} \equiv 2^{-2s} h(e+1)^{2} \equiv 1$

Hence

.

$$L_{d}^{*} = \frac{\rho + 1}{\rho^{2} + 1} \rho^{d} + \frac{\rho^{2} + \rho}{\rho^{2} + 1} \rho^{-d} = \frac{1}{\rho + 1} \rho^{d} + \frac{\rho}{\rho + 1} \cdot \frac{1}{\rho^{d}}$$

$$= \frac{1}{(\rho+1)\rho^{d-1}} (\rho^{2d-1} + 1)$$
 2.34

.

.

2.33

Case III.
$$L_0^* \equiv h^2 + e^2 \equiv 1 + 1 \equiv 0$$

 $L_1^* \equiv h^2 Y \equiv Y = \rho + \sigma$. (mod 2)

Thus

$$L_{d}^{*} = \frac{\rho(\rho + \rho^{-1}) + 0}{\rho^{2} + 1} \cdot \rho^{d} + \frac{\rho(\rho + \rho^{-1})}{\rho^{2} + 1} \cdot \frac{1}{\rho^{d}} = \rho^{d} + \frac{1}{\rho^{d}}$$
$$= \frac{1}{\rho^{d}} (\rho^{d} + 1)^{2} \cdot$$

Case IV.
$$L_{0}^{*} \equiv 2^{-r} \cdot e^{2} \equiv 0$$
 (mod 2)
 $L_{1}^{*} \equiv 2^{-r} \cdot h(e+1)^{2} \equiv 1$
 $\therefore L_{d}^{*} = \frac{\rho}{\rho^{2}+1} \cdot \rho^{d} + \frac{\rho}{\rho^{2}+1} \frac{1}{\rho^{d}} = \frac{1}{\rho^{2}+1} (\rho^{d+1} + \frac{1}{\rho^{d-1}})$
 $= \frac{1}{(\rho^{2}+1)\rho^{d-1}} (\rho^{d}+1)^{2}.$

Case V. $L_0^* \equiv 2^{-2s} \cdot e^2 \equiv 1$ (mod 2) $L_1^* \equiv 2^{-2s} \cdot h \equiv 0$. $. . L_{d}^{*} = \frac{1}{\rho^{2}+1} \rho^{d} + \frac{\rho^{2}}{\rho^{2}+1} \cdot \frac{1}{\rho^{d}} = \frac{1}{\rho^{2}+1} (\rho^{d} + \frac{1}{\rho^{d-2}})$

$$= \frac{1}{(\rho^2 + 1)\rho^{d-2}} (\rho^{d-1} + 1)^2 \cdot 2.37$$

2.35

2.36

<u>Proposition 2.1</u> Suppose that all the roots of $L_d^*(Y)$ lie in GF(4). Then d must satisfy the following conditions.

where f = 1 or 3 or 5.

<u>Proof.</u> Let 0, 1, w, w^2 be the elements of GF(4), where w, w^2 denote cube roots of 1. Now from the equation 2.30 we see that

Y = 0 corresponds to $\rho = 1$

Y = 1 corresponds to $\rho = w$ or w^2

and

$$Y = w$$
 or w^2 corresponds to $\rho = a$ root of

the equation

$$p^{2} + wp + 1 = 0$$
 or $p^{2} + w^{2}p + 1 = 0$. 2.39

These two equations do not have roots in GF(4). But

$$(x^{2}+wx+1)(x^{2}+w^{2}x+1) = x^{4}+x^{3}+x^{2}+x+1 = \frac{x^{3}+1}{x+1} \cdot 2.40$$

So Y = w or w^2 corresponds to $\rho = a$ primitive 5th root of 1, ε say. Therefore $L_d^*(Y)$ has roots in GF(4) if and only if the equation $N_d(\rho) = 0$ has its roots in the set

$$R = \{1, w, w^{2}, \varepsilon, \varepsilon^{2}, \varepsilon^{3}, \varepsilon^{4}\}$$
Now take $l = 2^{t} \times f$, where f is odd. Then $\rho^{l} + 1 = (\rho^{f} + 1)^{2t}$,
and the roots of $p^{f} + 1 = 0$ are all distinct and form a cyclic

group. A generator of this group is a primitive f^{th} root of unity. Therefore the roots of the equation $p^{f} + 1 = 0$ are not all in R unless $f \leq 5$. From this we get 2.38.

<u>Corollary 2.2</u>. The diameter d of a D-R graph with intersection matrix B must satisfy conditions 2.38.

<u>Proof</u>. By theorem 2 all the eigenvalues of the assumed graph must be of degree ≤ 2 over the rationals. Therefore the same must be true over GF(2). Now if such a graph exists the roots of the polynomial $H_d(Y)$ must be rational or quadratic. Thus the polynomial $[2^{-p} H_d(Y)]^* = L_d^*(Y)$ (regarded as a function of ρ) must have all its roots in the set R. This, by proposition 2.1, is true only when d satisfies the conditions 2.38

This proves theorem 3.

CHAPTER THREE

An upper bound of d

In this chapter we deal with the cases III, IV and V, aiming to obtain a bound for the diameter d of the assumed D-R graphs. We prove that there cannot be D-R graphs with intersection matrix B of diameter d > 81. To obtain that result we consider each of those three cases separately.

In case III, by looking into the polynomial $G_{d}^{}(x)$ we get that $t\leq 3$.

In cases IV and V the polynomial $H_d(Y)$ provides the information that $t \leq 4$.

Those two results, together with the result of theorem 3, give rise to the following .

Theorem 4. The only possible D-R graphs with intersection matrix B are those of diameter

d = 1,2 in case I, d = 1,2,3 in case II d = 1,2,4,8,3,6,12,24,5,10,20,40 in case III d = 1,2,4,8,16,3,6,12,24,48,5,10,20,40,80 in case IV d = 2,3,5,9,17,4,7,13,25,49,6,11,21,41,81 in case V.

Throughout this chapter the <u>order</u> of any integer I say, is defined to be the maximum power of 2 which divides I and it is denoted as ord(I).

With this notation we have

ord(h) = r, ord(e) = s.

 $1 \quad Case III \quad r = s = 0.$

From equations (2.3) and (2.4) we have

$$G_{d}^{*}(x) = xG_{d-1}^{*}(x) + G_{d-2}^{*}(x), d > 2$$
 3.1

$$G_{1}^{*}(x) = x$$
, $G_{2}^{*}(x) = x^{2}$. 3.2

Suppose that ρ,σ where $\rho^{-1} = \sigma$ are the roots of the equation

$$p^2 + xp + 1 = 0$$
 3.3

in characteristic 2.

Then the solution to the recurrence 3.1 is

 $A + B = G_{0}^{*}(x)$

$$G_{d}^{*}(x) = A\rho^{d} + B\sigma^{d} \qquad 3.4$$

where

$$A\rho + B\sigma = G_1^*(x)$$

from which we get that

Lemma 3.1. If $G_d(x)$ has all its roots rational or quadratic, then $2^{2^{t-1}}$ divides $G_d(a)$ for any even number a.

Proof. From equations 3.4 and 3.6 we get that

$$G_{d}^{*}(x) = \rho^{d} + \rho^{-d} = (\rho^{f} + \rho^{-f})^{2^{t}}$$
 3.7

Now, for any odd f, $x = \rho + \rho^{-1}$ divides $\rho^{f} + \rho^{-f}$. Therefore $x^{2^{t}}$ divides $G_{d}^{*}(x)$.

By hypothesis $G_d(x)$ is a product of at least $f \ge 2^{t-1}$ quadratic factors over the rationals. Reduced modulo 2 this product is divisible by x^{2^t} . Therefore at least 2^{t-1} factors
of $G_d^*(x)$ have constant term zero. Hence at least 2^{t-1} factors of $G_d(x)$ have even constant term. Thus $2^{2^{t-1}}$ divides the constant term of $G_d(x)$. Now let a be any even number. Then by the same argument $2^{2^{t-1}}$ divides the constant term of $G_d(x+a)$, which equals $G_d(a)$.

Corollary 3.1. ord (c-k)
$$\geq 2^{t-1}$$

<u>Proof.</u> By equations 2.3 and 2.4 we have that the constant term: of $G_d(x)$ is equal to

$$G_{d}(0) = (-h)^{\frac{d-2}{2}} . (c-k)$$
 . 3.8

In this case h is odd

... ord
$$(C-K) = ord(G_{d}(0)) \ge 2^{t-1}$$
, by lemma 3.1.

Lemma 3.2. Let ϕ, ψ be the roots of the equation

$$u^2 - xu + h = 0$$
 . 3.9

Then for any $d \geq 2$

$$G_{d}(x) = (x+c) \frac{\phi^{d} - \psi^{d}}{\phi - \psi} + (c-k) \frac{\phi^{d-1} - \psi^{d-1}}{\phi - \psi}$$
 3.10

provided $\phi \neq \psi$.

<u>Proof.</u> The roots of the equation 3.9 for $x = 2q \cos \alpha$, are $\phi, \psi = q.e^{\pm i\alpha}$.

Thus for any integer n we have

$$\phi^n - \psi^n = 2i q^n \cdot \sin n\alpha \quad . \qquad 3.11$$

Now by 2.1 and 1.13 we get

$$G_{d}(x) = q^{d-1} F_{d}(\cos \alpha) = (2q\cos \alpha + c) \cdot q^{d-1} \bigcup_{d=1}^{d-1} (\cos \alpha) + (c-1-q^{2}) q^{d-2} \bigcup_{d=2}^{d-2} (\cos \alpha) 3.12$$

But by 1.8 and 3.11 for every integer n, we have

$$q^{n} \cdot U_{n}(\cos \alpha) = q^{n} \frac{\sin(n+1)\alpha}{\sin \alpha} = \frac{\phi^{n+1} - \psi^{n+1}}{\phi - \psi} \cdot 3.13$$

Thus since $q^2 = k - 1$, from 3.12, we get 3.10.

Lemma 3.3. Let $x = \pm 2$ and ϕ, ψ be as in lemma 3.2. Let $d = 2^{t} x f$, where f is odd.

Then

(i)
$$\phi^{d} + \psi^{d} \equiv 2 \mod 4$$
.
(ii) ord $\frac{\phi^{d} - \psi^{d}}{\phi - \psi} = t$.
3.14
3.14

ł.

(i) We first note that in this case $\phi \cdot \psi = h$.

Also

$$\phi + \psi = \pm 2 \equiv 2 \mod 4$$

and

$$\phi^2 + \psi^2 = (\phi + \psi)^2 - 2\phi\psi = 4 - 2\phi\psi \equiv 2 \mod 4$$
.

Hence we have result for d = 1,2.

Suppose now that result holds for given d + 1 and d.

Then

$$\phi^{d+2} + \psi^{d+2} = (\phi + \psi)(\phi^{d+1} + \psi^{d+1}) - h(\phi^{d} + \psi^{d}) \equiv 2 \pmod{4} .$$
 3.16

Hence 3.14 holds by induction for every d.

(ii)
$$\frac{\phi^{d}-\psi^{d}}{\phi-\psi} = \frac{\phi^{f}-\psi^{f}}{\phi-\psi} \cdot \prod_{i=1}^{t} (\phi^{d/2^{i}} + \psi^{d/2^{i}}) \cdot 3.17$$

Now

and

ord
$$\prod_{i=1}^{t} (\phi^{d/2^{i}} + \psi^{d/2^{i}}) = \sum_{i=1}^{t} \operatorname{ord} (\phi^{d/2^{i}} + \psi^{d/2^{i}}) = t$$
 3.18

$$\frac{\phi^{f} - \psi^{f}}{\phi - \psi} = (\phi\psi)^{\frac{f-1}{2}} + \sum_{k=0}^{\frac{f-3}{2}} (\phi^{f-2k-1} + \psi^{f-2k-1}).(\phi\psi)^{k} . 3.19$$

Now
$$\phi \psi$$
 is odd and by (i) $\sum_{k=0}^{\frac{f-3}{2}} (\phi^{f-2k-1} + \psi^{f-2k-1}))$
is even $\therefore \frac{\phi^f - \psi^f}{\phi - \psi}$ is odd.

Hence

ord
$$\left(\frac{\phi^{d}-\psi^{d}}{\phi-\psi}\right) = \operatorname{ord}\left(\frac{\phi^{f}-\psi^{f}}{\phi-\psi}\right) + \operatorname{ord} \prod_{\hat{i}=1}^{t} \left(\phi^{d/2^{\hat{i}}}+\psi^{d/2^{\hat{i}}}\right)$$
$$= 0+t = t.$$

Proposition 3.1. Let r = s = 0, $d = 2^{t} \times f$. Then $t \leq 3$.

<u>Proof.</u> From lemma 3.2 for $x = \pm 2$ we get

$$G_{d}(\pm 2) = (\pm 2 + c) \frac{\phi^{d} - \psi^{d}}{\phi - \psi} + (c - k) \frac{\phi^{d-1} - \psi^{d-1}}{\phi - \psi}$$
 . 3.20

By lemma 3.1 $G_d(\pm 2)$ must be divisible by $2^{2^{t-1}}$

Now $\frac{\phi^{d-1} - \psi^{d-1}}{\phi - \psi}$ is an integer and by corollary 3.1 2^{2^{t-1}} divides c-k. Thus 2² must divide the first term of 3.20 which, by lemma 3.3, is equal to $(\pm 2 + c) \times 2^{t} \times odd$ number = T, say and since c is even either 4 divides c, which implies $\pm 2 + c \equiv 2 \pmod{4}$ or 4 does not divide c, which implies $\pm 2 + c \equiv 4 \pmod{8}$. Thus ord(T) $\leq t + 2$. 3.21 Hence $G_d(\pm 2)$ will be divisible by $2^{2^{t-1}}$ only if T is. This implies $2^{t-1} \leq \operatorname{ord}(T) \leq t+2$ 3.22 which is true only when $t \leq 3$.

Since $d = 2^{t} \times f$, f = 1 or 3 or 5 the above result proves Theorem 4 in case III.

34

§2. Cases IV and V

For the rest of this chapter we deal with case IV, where 2s > r > 0, $d = 2^{t} \times f$ and

Case V, where $r > 2s \ge 0$, $d = 2^{t} \times f + 1$. <u>Lemma 3.4</u> In cases IV and V $L_{d}^{*}(Y)$ is divisible by $Y^{2^{t}}$ and $2^{-p} H_{d}(a)$ is divisible by $2^{2^{t-1}}$ for every even a.

Proof. From lemma 2.3 we have

$$L_{d}^{*}(Y) = \begin{cases} \frac{1}{\rho + \rho^{-1}} [\rho^{d} + \rho^{-d}] & \text{in case IV} \\ \\ \frac{1}{\rho + \rho^{-1}} [\rho^{d-1} + \rho^{-(d-1)}] & \text{in case V}. \end{cases}$$

Call the R.H.S. of 3.23 $N_d(\rho)$. Then the equation $L_d^*(Y) = N_d(\rho)$ holds even if ρ is transcentendal over GF(2). Thus 3.23 holds identically if we put

$$Y = \rho + \rho^{-1} .$$

But $N_d(\rho) = \frac{(\rho^f + \rho^{-f})^{2^t}}{\rho + \rho^{-1}}$, and since f is odd we have

that
$$(\rho + \rho^{-1})^{2^{-1}}$$
 divides $N_d(\rho)$.

Therefore

$$Y^{2^{t}-1}$$
 divides $L_{d}^{*}(Y) = [2^{-p} H_{d}(Y)]^{*}$

Now, by theorem 2, $2^{-p} H_d(Y)$ is a product of at least f x 2^{t-1} quadratic factors. Reduced modulo 2, this product is divisible by $Y^{2^{t}-1}$. Therefore at least 2^{t-1} factors of $[2^{-p} H_d(Y)]^*$ have constant term zero. Hence at least 2^{t-1} factors of $2^{-p} H_d(Y)$ have an even constant term. Thus $2^{2^{t-1}}$ divides the constant term of $2^{-p} H_d(Y)$.

By the same argument, for any even a, $2^{2^{t-1}}$ divides the constant term of $2^{-p} H_d(Y+a)$, which equals $2^{-p} H_d(a)$.

Lemma 3.5.

(i) If 4 divides d then

$$H_d(0) = H_d(2) = (c-k)^2 = (h-e)^2$$
. 3.24

(ii) If 4 divides d-1 then $H_d(0) = -hc^2$ and $H_d(2) = -h(c^2-2h)$. 3.25

<u>Proof.</u> From definition 2.3 $K_{d}(Y) = -2(c-1)^{2} \cos 2(d-1)\alpha + 2h(c^{2}-2c+2)\cos 2d\alpha - 2h^{2}\cos 2(d+1)\alpha$ $M(Y) = 2[h^{2}+(c-1)^{2}+2h(c-1)\cos 2\alpha - hc^{2}]$ $(4-Y) H_{d}(Y) = M(Y) + K_{d}(Y)$.

Now by 2.6 Y = 0 => $\cos 2\alpha$ = -1 => $\alpha = \frac{\pi}{2}$

Thus

$$K_{d}(0) = \begin{cases} 2e^{2} + 2h(e^{2}+1) + 2h^{2} & \text{if } d \equiv 0 \pmod{4} \\ -2e^{2} - 2h(e^{2}+1) - 2h^{2} & \text{if } d \equiv 1 \pmod{4} \end{cases}$$

and

$$M(0) = 2h^2 + 2e^2 - 4he - 2h(e+1)^2$$

... by 3.26 we get

$$H_{d}(0) = \begin{cases} (h - e)^{2} & \text{if } d \equiv 0 \pmod{4} \\ -h(e + 1)^{2} & \text{if } d \equiv 1 \pmod{4} \end{cases}.$$

Next
$$Y = 2 \Rightarrow \cos 2\alpha = 0 \Rightarrow \alpha = \frac{\pi}{4}$$

Thus

$$K_{d}(2) = \begin{cases} 2h(e^{2} + 1) & \text{if } d \equiv 0 \pmod{4} \\ \\ 2(h^{2} - e^{2}) & \text{if } d \equiv 1 \pmod{4} \end{cases}$$

and

$$M(2) = 2h^2 + 2e^2 - 2h(e + 1)^2$$
.

... by 3.26 we get

$$H_{d}(2) = \begin{cases} (h - e)^{2} & \text{if } d \equiv 0 \pmod{4} \\ 2h^{2} - h(e+1)^{2} & \text{if } d \equiv 1 \pmod{4} \end{cases}$$

Lemma 3.6
$$H_d(4) = [d(h+e) + (h-e)]^2 - d^2 c^2 h$$
. 3.27
Proof By equation 2.6, $Y = 4 = 2 \cos^2 \alpha = 1 = 2 \alpha = 0$.

From 2.9 we have

$$H_{d}(Y) = h[(q \frac{\sin(d+1)\alpha}{\sin\alpha} + \frac{c-1}{q} \cdot \frac{\sin(d-1)\alpha}{\sin\alpha})^{2} - c^{2} \frac{\sin^{2} d\alpha}{\sin^{2} \alpha}]$$
On letting $\alpha \neq 0$ and applying L'Hopital's rule we get 3.27.

Case IV. 2s > r > 0. Here p = min(2s,r) = r.

By lemma 3.4 $2^{-r} H_d(a)$, where a is any even number, is divisible by $2^{2^{t-1}}$. Thus

ord
$$(H_d(a)) \ge r + 2^{t-1}$$
 . 3.28

Also by lemmas 3.5 and 3.6

$$H_{d}(2) = (h-e)^{2}$$
, $d \equiv 0 \pmod{4}$ 3.29

$$H_{d}(4) = [d(h+e) + (h-e)]^{2} - d^{2}(e+1)^{2}h$$
 3.30

Lemma 3.7. Let r > s. Then $t \leq 4$.

Proof. Since r > s > 0 from 3.29 and 3.30 we get

ord
$$(H_{d}(2)) = 2s$$
 3.31

ord
$$(H_{d}(4)) \ge \min(2s, 2t + r)$$
 3.32

where the equality holds only if $2s \neq 2t + r$. Thus if $2s \neq 2t + r$ we have

$$2t + r \ge ord(H_{d}(4))$$
 . 3.33

Now let 2s = 2t + r then 3.34

 $2t + r = ord(H_d(2))$ (by 3.31) . 3.35

.
$$2t + r \ge r + 2^{t-1}$$
 by 3.28 . $t \le 4$

Lemma 3.8. Let s > r. Then $t \leq 4$. Proof. In this case since s > r > 0ord $(H_d(2)) = 2r$ 3.36 and

ord $(H_d(4)) \ge \min(2r, 2t + r)$ 3.37

where the equality holds only if $r \neq 2t$.

$$2t + r \ge ord(H_{d}(4))$$
 . 3.38

When r = 2t, then by 3.36

$$r+2t = 2r = ord(H_{a}(2))$$
.

Thus from 3.28 we get that

$$2t + r \ge r + 2^{t-1}$$
, for any r.
... $t \le 4$.

Lemma 3.9 Let
$$s = r$$
. Then $t \leq 4$

<u>Proof</u>. Let ord (h+e) = r + u, and ord (h-e) = r + v. Now by 3.28 both $H_d(4)$ and $H_d(2)$ are of order greater than or equal to $r + 2^{t-1}$. Thus the same will be true for the number

$$H_{d}(4) - H_{d}(2) = d^{2}[(h+e)^{2} - h(e+1)^{2}] + 2d(h^{2}-e^{2})$$
 3.40
= $T_{1} + T_{2}$, say.

Now, $\operatorname{ord}(T_1) = 2t+r$ and $\operatorname{ord}(T_2) = t+2r+1+u+v$. Therefore if $\operatorname{ord}(T_1) \neq \operatorname{ord}(T_2)$ then

$$\operatorname{ord}(H_{d}(4) - H_{d}(2)) \leq 2t + r$$
. 3.41

Thus

$$2t + r \ge r + 2^{t-1} \quad \cdots \quad t \le 4.$$

Next suppose that $ord(T_1) = ord(T_2)$, then

$$t - l = r + u + v$$
. 3.42

But by 3.28

$$r + 2^{t-1} \leq \operatorname{ord}(H_d(2)) = 2r + 2v$$
, 3.43

...
$$r + 2^{r+u+v} \leq 2r + 2v < 2(r + u + v)$$
 which is

impossible. Thus $ord(T_1) \neq ord(T_2)$.

From lemmas 3.7, 3.8 and 3.9 we have that the order of the diameter d in case IV is less than or equal to 4. That proves theorem 4 in case IV.

<u>Case V</u> $r > 2s \ge 0$. In this case $p = \min(r, 2s) = 2s$. For any even number a we have, by lemma 3.4 that $2^{-2s} H_d(a)$ is divisible by $2^{2^{t-1}}$. Thus

$$ord(H_d(a)) \ge 2s + 2^{t-1}$$
. 3.44

By lemmas 3.5 and 3.6 we have

$$H_{d}(0) = -hc^{2} = -h(e+1)^{2}, \quad d \equiv 1 \pmod{4}$$

$$H_{d}(4) = [d(h+e) + (h-e)]^{2} - d^{2}.hc^{2}$$

$$= [h(d+1) + e(d-1)]^{2} + d^{2} H_{d}(0) . \qquad 3.45$$

Here $d-1 = 2^{t} \times f$ and we will prove that $t \leq 4$. We suppose that $t \geq 2$. Then ord(d+1) = 1.

Lemma 3.10. Let r > 2s > 0. Then $t \leq 4$. Proof. Since s > 0, e + 1 is odd. Thus

ord
$$(H_{d}(0)) = r$$
 . 3.46

Thus by 3.44 we get that

$$r \ge 2s + 2^{t-1}$$
. 3.47

Now since both $H_d(4)$ and $d^2 H_d(0)$ have order greater than or equal to $2s + 2^{t-1}$ the same will be true for

$$H_{d}(4) - d^{2} H_{d}(0) = [h(d+1) + e(d-1)]^{2}$$
. 3.48

But ord $(H_d(4) - d^2H_d(0)) \ge 2 \times \min(r+1, t+s)$ where inequality holds only when r+1 = t+s. In which case from 3.47 we get that

 $r \ge 2s + 2^{r-s}$ which is impossible.

Thus always $r + l \neq t + s$. Hence

$$\operatorname{ord}(H_{d}(4) - d^{2}H_{d}(0)) = 2 \times \min(r+1, t+s) \leq 2t + 2s$$

 $2^{t-1} + 2s \leq 2t + 2s$ 3.49

which is true only when $t \leq 4$.

Lemma 3.11. Let r > 2s = 0. Then $t \leq 4$. Proof. Let ord(e+1) = u. Then

$$ord(H_d(0)) = r + 2u$$
 . 3.50

Since e is odd

••••

$$\operatorname{ord}[H_{d}(4) - d^{2} H_{d}(0)] \ge 2 \times \min(r + 1, t)$$
 . 3.51

If $r \ddagger t-1$, then equality holds in (3.51) so ord[H_d(4) - d²H_d(0)] $\leq 2t$ Thus from 3.51 and 3.44, for s = 0, we have

 $2t \geq 2^{t-1} \cdot t \leq 4$.

41

Now if r = t-1, we consider the number

$$H_{d}(4) - d^{2}H_{d}(2) = h^{2}[(d+1)^{2} - 2d^{2}] + 2h(d^{2}-1).e + (d-1)^{2}e$$

whose order must be greater than or equal to 2^{t-1} . Now the orders of the terms in the R H S when r = t-1 are

... ord(
$$H_d(4) - d^2 H_d(2)$$
) = 2t - 1
... 2t-1 $\geq 2^{t-1}$... t ≤ 3 .

From lemmas 3.10 and 3.11 we have that in case V t is less than or equal to 4.

This proves theorem 4 in case V $\ensuremath{\boldsymbol{.}}$

CHAPTER FOUR

Further Results

In the previous chapters we have proved that the only possible D-R graphs with intersection matrix B are those of diameter $d \leq 81$.

In this chapter we classify the assumed graphs according to the value of f and we prove.

Theorem 5. The only possible D-R graphs with intersection matrix B are those of diameter

d =	1,2,3,4,5,8,9	when	f = 1
d =	3,4,6,7,12,13,24,25	when	f = 3
d =	5,6,10,11	when	f = 5.

To obtain this result we consider each one of those classes separately. For each one we obtain certain arithmetical conditions which are necessary for the existence of the corresponding graph.

Those conditions alone provide the answer for f = 1. For the rest of the cases, we use the computer-algebra system Reduce 2 [10] (implemented on the computer at Newcastle).

For each value of d we calculate $H_d(Y)$ reduced to various module. Then we observe that not all those polynomials satisfy the necessary conditions. Definition 4.1. We define the order of the linear polynomial
AY + B to be the min(ord(A), ord(B)).

@ means reduction modulo Y² - Y - 1.
We also define
 u = ord(h - e)
 v = ord(h + e)
 w = ord(e + 1)
 p = min(r,2s)
 r = ord(h)

s = ord(e)

t = ord(d) or ord(d-1) according to case.

Throughout this chapter the Greek letters ε and θ mean even numbers and odd numbers respectively.

§1. Graphs of diameter
$$d = 2^t$$
 or 2^t+1 .

In chapter three we have proved that $t \leq 3$ in case III and t ≤ 4 in cases IV and V. Here we prove that t = 4 is impossible.

Lemma 4.1. If $H_d(Y)$ is a product of rational or quadratic factors, then reduced modulo $Y^2 + \varepsilon Y$ will be divisible by $2^{2^{t-1}+p}$.

Proof. By lemma 2.3 for f = 1 in cases IV and V we have

$$L_{d}^{*}(Y) = Y^{2^{t}-1}$$
 4.1

where $L_d(Y) = 2^{-p} H_d(Y)$. By hypothesis the polynomial $L_d(Y)$ is a product of at least 2^{t-1} quadratic factors.

Reduced modulo 2 this product has the form 4.1. Thus $L_d(Y)$ will be a product of 2^{t-1} factors of the type $Y^2 + \epsilon Y + \epsilon$ over the rationals. But

$$Y^{2} + \varepsilon Y + \varepsilon \equiv (\varepsilon Y + \varepsilon) (mod(Y^{2} + \varepsilon Y)) . \qquad 4.2$$

Thus

$$L_{d}(Y) = P(Y).(Y^{2} + \varepsilon Y) + 2^{2}.Q(Y)$$
 4.3

where Q(Y) is a polynomial of degree 2^{t-1} .

Therefore

$$L_{d}(Y) \equiv 2^{2^{t-1}} (a_{1}Y + b)(mod(Y^{2} + \epsilon Y))$$
 . 4.4

From which we get the stated result.

Lemma 4.2. Let $t \ge 2$. Then

$$H_{d}(Y) \equiv \begin{cases} (h-e)^{2} (mod(Y^{2} - 2Y)) & \text{if } d = 2^{t} \\ (h^{2} \cdot Y - h(e+1)^{2})(mod(Y^{2} - 2Y)) & \text{if } d = 2^{t} + 1 \end{cases}$$

Proof
$$H_d(Y) \equiv (AY + B) \mod Y^2 - 2Y$$

where

 $2A + B = H_{d}(2)$ $B = H_{d}(0)$. 4.6

By lemma 3.5

$$H_{d}(0) = H_{d}(2) = (h-e)^{2}$$
, when $d \equiv 0 \pmod{4}$
 $H_{d}(0) = -h(e+1)^{2}$

and

$$H_{d}(0) = -h(e + 1)^{2}$$

when $d \equiv 1 \pmod{4}$
 $H_{d}(2) = 2h^{2} - h(e+1)^{2}$

Now by 4.6

$$A = 2^{-1} [H_d(2) - H_d(0)], \quad B = H_d(0)$$
 4.7

from which we get the stated results .

<u>Definition 4.2</u> © means reduction modulo $Y^2 - 4Y$ <u>Lemma 4.3</u>. Let ord(H_d(Y)(mod Y^2-2Y)) $\geq 8 + p$.

Then

I ord(
$$H_{16}^{\Theta}(Y)$$
) $\leq 6 + r$

II $\operatorname{ord}(H_{17}^{0}(Y)) \leq 6 + 2s$.

Proof.

$$H_{d}(Y) \equiv CY + D \mod Y^{2} - 4Y$$

where $4C + D = H_d(4)$

and $D = H_{d}(0)$

Thus

$$C = 2^{-2}[H_d(4) - H_d(0)]$$
, $D = H_d(0)$ 4.9

$$H_d^{\Theta}(Y) = 2^{-2} [H_d(4) - H_d(0)] \cdot Y + H_d(0)$$
 . 4.10

By lemma 3.6

$$H_{d}(4) = [d(h+e) + (h-e)]^{2} - d^{2}h(e+1)^{2}$$

and by lemma 3.5

$$H_{d}(0) = (h-e)^{2}$$
, when $d \equiv 0 \pmod{4}$
 $H_{d}(0) = -h(e+1)^{2}$, when $d \equiv 1 \pmod{4}$.

Thus when d = 16

$$H_{16}^{0}(Y) = 8[8(h-1)(h-e^{2}) + (h^{2} - e^{2})]Y + (h-e)^{2}$$
$$= C_{1}Y + D_{1}$$
4.11

and when d = 17

$$H_{17}^{\Theta}(Y) = [81h^{2} + 64e^{2} - 72h(e^{2}+1)]Y - h(e+1)^{2}$$

= $C_{2}Y + D_{2}$. 4.12

I. d = 16 corresponds to the case IV, where 2s > r > 0. By hypothesis and by lemma 4.2 we have

$$8 + r = 8 + p \leq \operatorname{ord}[H_{d}(Y) \mod Y^{2} - 2Y] = \operatorname{ord}(h-e)^{2} = 2u \qquad 4.13$$

where
$$u = \begin{cases} r & \text{when } s > r \\ s & \text{when } r > s \\ r + q, q \ge 1 & \text{when } r = s \end{cases}$$
 4.14

Now the orders of the terms in C_1 for d = 16 are

6 + r, 3 + u + v

where $u + v = 2u \ge 8 + r$ when $r \ddagger s$ and $u + v \ge 2r + 3$ when r = s.

Thus always 6 + r < 3 + u + v... $ord(C_1) = 6 + r$. 4.16

II. d = 17 corresponds to the case V where $r > 2s \ge 0$. Now if s > 0 by hypothesis and lemma 4.2 we have that $r = ord(B) \ge 8 + 2s$.

and since for s > 0 the orders of the terms in C_2 are

$$2r, 6 + 2s, 3 + r$$

we get that $\operatorname{ord}(C_2) = 6 + 2s$.

W

Next let s = 0. Then by lemma 4.2

$$2r = ord(A) \geq 8 \qquad 4.19$$

 $r \geq 4$. The orders of the terms in C_2 thus when s = 0 are

2r, 6, 4 + r
4.20
thus since
$$r \ge 4$$
 ord(C₂) = 6.
Hence by 4.16, 4.18, 4.21 and definition 4.1
we get the stated results.

Corollary 4.1. There is no graph of diameter d = 16 or 17. Proof. Suppose that such graphs exist. Then the corresponding polynomials $H_{16}(Y)$ and $H_{17}(Y)$ will factorize into quadratic factors. Then by lemma 4.1 $H_{16}(Y)$ and $H_{17}(Y)$ reduced modulo $Y^2 + \epsilon Y$ for any even ϵ will be of order greater than or equal to 8 + p. This contradicts lemma 4.3.

Thus we have proved theorem 5 in the case f = 1.

§2. Graphs of diameter $d = 2^{t} \times 3$ or $2^{t} \times 3 + 1$

From theorem 4 we have that the maximal graphs of this class who possibly exist are those of diameter d = 48 in case IV and d = 49 in case V. Here we prove that no graphs of these diameters exist.

Lemma 4.4. If the D-R graph with diameter

d = $2^{t} \times 3$ or $2^{t} \times 3 + 1$ exists. Then $L_{d}^{*}(Y)$ is divisible by $(Y^{2} + 1)^{2^{t}}$ and $2^{-p}H_{d}(\theta)$ is divisible by $2^{2^{t}}$ for every odd θ .

Proof. From lemma 2.3 for f = 3 we have

$$L_{d}^{*}(Y) = \begin{cases} (\rho^{3} + \rho^{-3})^{2^{L}} & \text{in case III} \\ (\rho^{3} + \rho^{-3})^{2} \cdot (\rho + \rho^{-1}) & \text{in case IV and V} \end{cases}$$

Call the R.H.S of 4.22 $N_d(\rho)$. Then the equation $L_d^*(Y) = N_d(\rho)$ holds even if ρ is transcendental over GF(2). Thus 4.22 holds identically if we put $Y = \rho + \rho^{-1}$. Now $N_d(\rho)$ is divisible by $(\rho^2 + \rho^{-2} + 1)^{2^t}$ and since $\rho^2 + \rho^{-2} = Y^2$ (in GF(2)) then

$$(Y^{2} + 1)^{2^{t}}$$
 divides $L_{d}^{*}(Y) = [2^{-p} H_{d}(Y)]^{*}$

By theorem 2 if the graph of diameter d exists the polynomial $2^{-p} H_d(Y)$ will be a product of at least f x 2^{t-1} quadratic factors over the rationals. Reduced modulo 2, this product when f = 3 is divisible by $(Y^2 + 1)^{2^t}$. Therefore at least 2^t factors of $[2^{-p} H_d(Y)]^*$ will have the form $Y^2 + Y$ or $Y^2 + 1$.

Hence at least 2^{t} quadratic factors of $2^{-p}H_{d}(Y)$ will have the form $Y^2 + \theta Y + \varepsilon$ or $Y^2 + \varepsilon Y + \theta$. Thus since the value of each one of those terms at Y = θ is even we get the stated result. Lemma 4.5

$$H_{d}(1) = \begin{cases} (h-e)^{2} , & \text{when } d \equiv 0 \pmod{3} \\ h^{2} - h(e+1)^{2} , & \text{when } d \equiv 1 \pmod{3} \end{cases}$$

Proof. By definition 2.2 $Y = 2 \cos 2\alpha + 2$. Thus for Y = 1, $\alpha = \frac{2\pi}{3}$. By definition 2.3

$$M(1) = 2he + 2(h-e)^{2} - 2h(e+1)^{2}$$
4.23

$$K_{d}(1) = -2e^{2}\cos(d-1)\frac{4\pi}{3} + 2h(e^{2}+1)\cos\frac{4\pi}{3}$$
$$- 2h^{2}\cos(d+1)\frac{4\pi}{3} \qquad 4.24$$

$$3.H_d(1) = K_d(1) + M(1)$$
 4.25

Let $d \equiv 0 \pmod{3}$. Then

2

$$K_{d}(1) = -2e^{2} \cos \frac{4\pi}{3} + 2h(e^{2}+1) - 2h^{2} \cos \frac{4\pi}{3}$$
$$= e^{2} + 2h(e^{2}+1) + h^{2}$$
4.26

and from 4.25 we get

$$H_{d}(1) = (h-e)^{2}, d \equiv 0 \pmod{3}$$
.

Let $d \equiv 1 \pmod{3}$. Then

$$K_{d}(1) = -2e^{2} + 2h(e^{2}+1) \cos\frac{4\pi}{3} - 2h^{2} \cos\frac{2\pi}{3}$$
$$= -2e^{2} - h(e^{2}+1) + h^{2} .$$

Thus $H_d(1) = h^2 - h(e+1)^2$, $d \equiv 1(mod3)$.

Lemma 4.6. Let 2s > r > 0. Let d = 48 (so t = 4) and $\operatorname{ord}(\operatorname{H}_{48}(1)) \ge 16 + r$. Then $\operatorname{ord}(\operatorname{H}_{48}(-3)) = 12 + r$. Proof. By hypothesis and lemma 4.5 we have $2u = \operatorname{ord}(h-e)^2 = \operatorname{ord}(\operatorname{H}_{48}(1)) \ge 16 + r$ 4.28 Now by computer calculations we get $\operatorname{H}_{48}(-3) = 2^{13} \cdot 5 \cdot h^2 + 2^{12} \cdot 13 \cdot e^2 + 2^6 \cdot 47 \cdot (h^2 - e^2) + 2^{12} \cdot h(e^2 + 1) + (h-e)^2 \cdot 4.29$ This result is reduced modulo 2^{16} since otherwise the result would be intolerable. The orders of the terms in 4.29 are 13 + 2r, 12 + 2s, 6 + u + v, 12 + r, 2u . 4.30 Now if $r \ddagger s$ $v = \operatorname{ord}(h+e) = \operatorname{ord}(h-e) = u \ge 8 + \frac{r}{2}$ by (4.28) and if r = s then $u \ge 8 + \frac{r}{2}$ by (4.28) and v > r

Thus always 12 + r < 6 + u + v and all the other terms of 4.30 are greater than 12 + r.

From which we get that $H_{\mu8}(-3)$ is of order 12 + r.

Lemma 4.7. Let $r > 2s \ge 0$. Let d = 49 (so t = 4) and ord($H_{49}(1)$) $\ge 16 + 2s$. Then ord ($H_{49}(-3)$) = 12 + 2s.

<u>Proof.</u> We first consider the case s > 0. Here by hypothesis and lemma 4.5 we have

$$r = ord (H_{\mu 0}(1)) \ge 16 + 2s$$
.

Now by computer we calculate $H_{49}(-3)$ reduced modulo 2^{16} and we get

$$H_{49}(-3) = -43715h^2 - 2^6.687.h(e^2+1) - h(e+1)^2 - 2^{12}.11.e^2$$
 . 4.32

The orders of the terms here are

and since (by 4.31) $r \ge 16 + 2s$ we have that

$$rd(H_{uq}(-3)) = 12+2s$$
 .

Now let s = 0.

Consider

$$H_{49}(-3) - H_{49}(1) = -2^2 \cdot 10929h^2 - 2^6 \cdot 687h(e^2 + 1) - 2^{12} \cdot 11.e^2$$
 . 4.34

Here the orders are

Now

$$12 < 7 + r < 2 + 2r , \text{ when } r > 5$$

$$12 = 7 + r = 2 + 2r , \text{ when } r = 5$$

$$2 + 2r < 7 + r < 12 , \text{ when } r < 5 .$$

Thus

ord
$$(H_{\mu q}(-3) - H_{\mu q}(1)) \leq 12$$
 4.36

and since by hypothesis $\operatorname{ord}(H_{49}(1)) \ge 16$ we have that $\operatorname{ord}(H_{49}(-3)) \le 12$.

Corollary 4.2. There is no graph of diameter d = 48 or 49.

<u>Proof.</u> Suppose that such graphs exist. Then by lemma 4.4 $H_{48}(\theta)$ and $H_{49}(\theta)$ will have orders greater than or equal to 16 + p for any odd numbers θ . By lemmas 4.6 and 4.7 when $\theta = -3$ this is not so.

This proves theorem 5 in the case f = 3.

Graphs of diameter
$$d = 2^{t} \times 5$$
 or $2^{t} \times 5 + 1$

In chapter three we have proved that possible graphs of this class are those of diameter

5, 10, 20, 40, 80 when
$$d = 2^T \times 5$$

and

6, 11, 21, 41, 81 when
$$d = 2^{t} \times 5 + 1$$
.

Here we prove that the only possible graphs are those of diameter d = 5, 6, 10 or 11.

§3. Necessary conditions for graphs of diameter $d = 2^{t} \times 5$ or $2^{t} \times 5 + 1$.

<u>Lemma 4.8</u>. If a graph of diameter $d = 2^{t} \times 5$ or $d = 2^{t} \times 5 + 1$ exists then the polynomial $H_{d}(Y)$ reduced modulo $Y^{2} + \theta Y + \theta$ will be divisible by $2^{2^{t-1}+p}$. Proof.

By lemma 2.3 for f = 5 we have

 $L_{d}^{*} = \begin{cases} (\rho^{5} + \rho^{-5})^{2^{t}} & \text{in case III} \\ (\rho^{5} + \rho^{-5})^{2^{t}} (\rho + \rho^{-1})^{-1} & \text{in cases IV and V} \end{cases}$

where $\rho + \rho^{-1} = Y$. Now in GF(2)

$$\rho^{5} + \rho^{-5} = (\rho + \rho^{-1}) [(\rho + \rho^{-1})^{2} + (\rho + \rho^{-1}) + 1]^{2}$$

$$L_{d}^{*}(Y) = \begin{cases} Y^{2^{t}}(Y^{2} + Y + 1)^{2^{t+1}} & \text{in case III} \\ \\ Y^{2^{t}-1}(Y^{2} + Y + 1)^{2^{t+1}} & \text{in cases IV and V}. \end{cases}$$

By theorem 2, if the assumed graph exists, the polynomial $L_d(Y) = 2^{-p} H_d(Y)$ will be a product of linear or quadratic factors over the rationals. Reduced modulo 2 this product has 2^{t+1} irreducible quadratic factors of the form $Y^2 + Y + 1$. Hence the polynomial $2^{-p} H_d(Y)$ has at least 2^{t+1} irreducible (over the rationals) quadratic factors of the form $Y^2 + \theta Y + \theta$. Now for each one of these factors we have

$$Y^{2} + \theta Y + \theta \equiv \varepsilon Y + \varepsilon \pmod{Y^{2} + \theta Y + \theta}$$
 4.39

Thus

$$2^{-p} H_{d}(Y) = P(Y).(Y^{2} + \theta Y + \theta) + 2^{2^{t+1}}.Q(Y)$$
 4.40

where Q(Y) is a polynomial of degree $\leq 2^{t}$.

54

4.38

Therefore

$$2^{-p} H_{d}(Y) \equiv 2^{2^{t+1}} (AY + B)(modY^{2} + \theta Y + \theta)$$
 . 4.41

Now since $Y^2 + \theta Y + \theta$ is monic and Q(Y) has integer coefficients we have that A,B are integers. Thus $2^{-p}H(Y)$ reduced modulo $Y^2 + \theta Y + \theta$ is divisible by $2^{2^{t+1}}$. Hence result.

Lemma 4.9.

$$H_{d}(Y) = \begin{cases} (h-e)^{2} \pmod{Y^{2} - 3Y + 1} & \text{if } d \equiv 0 \pmod{5} \\ (h^{2}Y-h(e+1)^{2}) \pmod{Y^{2}-3Y+1} & \text{if } d \equiv 1 \pmod{5} \end{cases}$$

<u>Proof.</u> Let Y_1, Y_2 be the roots of $Y^2 - 3Y + 1 = 0$. Then

$$H_{d}(Y) = P(Y).(Y^{2}-3Y+1) + AY + B$$
 4.42

where

$$AY_{1} + B = H_{d}(Y_{1})$$

 $AY_{2} + B = H_{d}(Y_{2})$.
4.43

Now $Y_1 = \frac{3 + \sqrt{5}}{2}$, $Y_2 = \frac{3 - \sqrt{5}}{2}$. By definition

2.2 equation (2.6) $Y = 2 \cos 2\alpha + 2$. Thus

$$\cos 2\alpha = \frac{-1 + \sqrt{5}}{4}$$
 or $\cos 2\alpha = -\frac{1 + \sqrt{5}}{4}$

Hence

$$Y_1$$
 corresponds to $\alpha = \frac{\pi}{5}$

 Y_2 corresponds to $\alpha = \frac{2\pi}{5}$

55

By definition 2.3

$$\begin{split} \kappa_{d}(Y) &= -2e^{2}\cos(d-1) \cdot 2\alpha + 2h(e^{2}+1)\cos d \cdot 2\alpha - 2h^{2}\cos(d+1)2\alpha \\ M(Y) &= 2[h e Y + (h - e)^{2} - h(e + 1)^{2}] \\ \text{Thus when } d \equiv 0 \pmod{5} \\ \kappa_{d}(Y_{1}) &= 2h(e^{2}+1) - 2\cos\frac{2\pi}{5}(h^{2} + e^{2}) \\ \kappa_{d}(Y_{2}) &= 2h(e^{2}+1) - 2\cos\frac{4\pi}{5}(h^{2} + e^{2}) \\ \text{and} \end{split}$$

$$M(Y_1) = 2h^2 + 2e^2 + 4he \cdot \cos \frac{2\pi}{5} - 2h(e+1)^2$$
$$M(Y_2) = 2h^2 + 2e^2 + 4he \cdot \cos \frac{4\pi}{5} - 2h(e+1)^2$$

Now for every $Y \neq 4$

$$H_{d}(Y) = [K_{d}(Y) + M(Y)](4-Y)^{-1}$$

Thus

$$H_{d}(Y_{1}) = H_{d}(Y_{2}) = (h-e)^{2}$$
 4.44

and from 4.43 we have

$$A = 0, B = (h-e)^2$$
. 4.45

In the case $d \equiv 1 \pmod{5}$, working similarly we have

$$A = h^2$$
, $B = -h(e+1)^2$. 4.46

4.45 and 4.46 prove lemma 4.9.

<u>Corollary 4.1</u>. The only possible D-R graphs with intersection matrix B and diameter $d = 2^{t} \times 5$ or $2^{t} \times 5 + 1$ are those for which

$$2 \times \text{ord}(h-e) \ge 2^{t+1} + p$$
, when $d \equiv 0 \pmod{5}$

or

ord
$$(h^2 Y - h(e+1)^2) \ge 2^{t+1} + p$$
, when $d \equiv 1 \pmod{5}$
By lemma 4.8 if such a graph exists then the

<u>Proof.</u> By lemma 4.8 if such a graph exists then the corresponding polynomial $H_d(Y)$ reduced modulo $Y^2 + \theta Y + \theta$ for any odd numbers θ must be divisible by $2^{2^{t+1}+p}$. By lemma 4.9.

$$H_{d}(Y) \equiv \begin{cases} (h-e)^{2} \pmod{2^{2}-3Y+1}, & d \equiv 0 \pmod{5} \\ (h^{2}Y-h(e+1)^{2})(\mod Y^{2}-3Y+1), & d \equiv 1 \pmod{5} \end{cases}$$

Hence result.

§4. Graphs with diameter
$$d = 2^{t} \times 5$$
.

These Graphs correspond to the cases III where s = r = 0 and IV where 2s > r > 0.

By corollary 4.1 we have that the only possible graphs of this class are those for which

$$2u = 2 \times ord(h-e) \ge 2^{t+1} + r.$$
 4.47

Here we note that

$$u = v = \begin{cases} r, when s > r \\ s, when s < r \end{cases}$$
 4.48

and

$$u + v > 2^{t} + r$$
, when $s = r$. 4.49

Since
$$u \ge 2^t + \frac{r}{2}$$
 by (4.47) and $v \ge \min(r,s) > \frac{r}{2}$

In the following we assume that condition 4.47 holds. We also recall that \oplus means reduction modulo $Y^2 Y - 1$ Lemma 4.10. Let t = 2,3 or 4. Then

$$\operatorname{ord}(\operatorname{H}_{\operatorname{d}}^{\Theta}(\operatorname{Y})) \leq 2(t+1) + r$$
.

<u>Proof</u> We calculate H_{20}^{\oplus} , H_{40}^{\oplus} and H_{80}^{\oplus} on computer. This gives intolerably large numbers. To avoid this we have reduced all numerical coefficients modulo 2^{16} and we get.

$$H_{20}^{\oplus}(Y) = [2^{6}.191.h(e^{2}+1) + 2^{7}.83.e^{2} + 2^{5}.667(h^{2}-e^{2})]Y$$

+ 2⁶.25h(e^{2}+1) + 2⁶.883e^{2} + (h-e)^{2} - 2^{3}.2101 (h^{2}-e^{2})
= A₁Y + B₁ . 4.50

$$H_{40}^{\oplus}(Y) = [2^{8}.111 h(e^{2}+1) - 2^{9}.29.e^{2} + 2^{6}.513(h^{2}-e^{2})]Y$$

- 2⁸.87.h(e²+1) - 2⁸.29.e² + (h-e)² - 2⁴.2441(h²-e²)
= A₂Y + B₂ 4.51

and

$$H_{80}^{\oplus}(Y) = [-2^{10} \cdot 17 \cdot h(e^{2}+1) + 2^{11} \cdot 3 \cdot e^{2} - 2^{7} \cdot 115 (h^{2}-e^{2})]Y$$

+ 2^{10} \cdot 41 \cdot h(e^{2}+1) - 2^{10} \cdot 29 \cdot e^{2} + (h-e)^{2} + 2^{5} \cdot 1807(h^{2}-e^{2})
= A₃Y + B₃ . 4.52

Now if 2s > r > 0 the orders of the terms in the constant term B_i , i = 1,2,3 are

2t + 2 + r, 2t + 2 + 2s, 2u, t + 1 + u + v 4.53 and since $2u \ge 2^{t+1} + r$ and $u + v > 2^{t} + r$

for t = 2,3 or 4 (so d = 20, 40, 80) we get that

$$ord(B_{1}) = 2t + 2 + r$$
 . 4.54

Next if s = r = 0 the orders in the constant term become

$$2t + 3$$
, $2t + 2$, $2u$, $t + 1 + u + v$ 4.55

where $2u \ge 2^{t+1}$ and $u + v > 2^{t}$.

Thus

 $ord(B_{i}) = 2t + 2$.

Corollary 4.2. If a graph of diameter $d = 2^{t} \times 5$ exists then $t \leq 1$.

<u>Proof.</u> By lemma 4.8 the corresponding polynomial $H_d(Y)$ reduced modulo $Y^2 + \theta Y + \theta$ where θ is any odd numbers will be of order greater than or equal to $2^{t+1} + r$.

By lemma 4.10 for t = 2,3,4

$$2(t+1) + r \ge ord(H_d^{\theta}(Y)) \ge 2^{t+1} + r$$

which is impossible.

Graphs with diameter $d = 2^{t} \times 5 + 1$ \$5.

Graphs of this diameter correspond to the case V where $r > 2s \ge 0.$

By corollary 4.1 there is no graph of this type unless $ord(h^2Y - h(e+1)^2) \ge 2^{t+1} + 2s$. From this we get that

$$r \ge 2^{t+1} + 2s , \qquad \text{when } s \neq 0 \qquad 4.56$$

and
$$\min(2r, r + 2w) \ge 2^{t+1} \qquad \text{when } s = 0 \qquad . \qquad 4.57$$

Lemma 4.11. Let
$$t = 2,3$$
 or 4. Then
 $ord(H_d^{\Theta}(Y)) \leq 2(t+1) + 2s$.

Proof For the same reason as in lemma 4.10 the polynomials $H_{21}^{\oplus}(Y)$, $H_{41}^{\oplus}(Y)$ and $H_{81}^{\oplus}(Y)$ have been calculated modulo 2^{16} . These calculations give

$$H_{21}^{\oplus}(Y) = [-25927h^{2} - 2^{5}.667 h(e^{2}+1) - 2^{6}.191 e^{2}]Y + 2^{4}.3535 h^{2} - h(e+1)^{2} + 2^{3}.2101h(e^{2}+1) - 2^{6}.25.e^{2} = A_{1}Y + B_{1} .$$
4.58

$$H_{41}^{\oplus}(Y) = [-43471.h^{2} - 2^{6}.513 h(e^{2}+1) - 2^{8}.111 e^{2}]Y + 2^{5}.723 h^{2} - h(e^{2}+1) + 2^{4}.2441 h(e^{2}+1) + 2^{8}.87.e^{2} = A_{2}Y + B_{2}$$
4.59

and

$$H_{81}^{\Theta}(Y) = [55137 h^{2} + 2^{7}.115 h(e^{2}+1) + 2^{10}.17.e^{2}]Y$$

+ 2⁶.357 h² - h(e+1)² - 2⁵.1807 h(e²+1) - 2¹⁰.41.e²
= A₃Y + B₃ . 4.60

Now if $s \neq 0$ the orders of the terms in the coefficient A_i (i = 1,2,3) of Y are

$$2r, t + 3 + r, 2t + 2 + 2s$$
 4.61

where t = 2,3 or 4 (so d = 21, 41 or 81). Thus by 4.56 we have that

$$ord(A_i) = 2t + 2 + 2s$$
, if $s > 0$. 4.62
Next let $s = 0$. Then the orders of the terms in

 A_{i} , i = 1,2,3 become for t = 2,3 or 4

$$2r, t + 4 + r, 2t + 2$$
 4.63

and by 4.57 we have that $r > 2^{t}$. Then ord(A_i) = 2t + 2.

Corollary 4.3. If a graph of diameter $d = 2^{t} \times 5 + 1$ exists then $t \leq 1$.

<u>Proof.</u> By lemmas 4.8 and 4.11 if such a graph exists then for t = 2,3,4

$$2(t+1) + 2s \ge \operatorname{ord}(\operatorname{H}_{d}^{\oplus}(Y)) \ge 2^{t+1} + 2s$$

which is impossible.

Corollaries 4.2 and 4.3 prove theorem 5 in the case f = 5.

CHAPTER FIVE

The impossibility of graphs with d = 25 or 24.

In this chapter we deal with graphs of diameter d = 25 or 24, and we suppose that these graphs exist. This assumption together with the theorems of Bannai and Ito [2] and Dumas [7] implies that the coefficients of the polynomials $H_{25}(z)$ and $H_{24}(z)$. where z = Y-1 must be divisible by certain powers of 2. But, by computing the actual coefficients, we see that this is not always so.

Thus we prove

Theorem 6. The only possible D-R graphs with intersection matrix B are those of diameter $1 \leq d \leq 13$.

§1.

Newton Polygons

Consider the polynomial

$$P(x) = a_n x^n + a_{n-1} x^{n-1} + \dots + a_1 x^n + a_0, a_n a_0 \neq 0$$

with rational coefficients.

For the prime number q, this polynomial can be written in the form

$$P(x) = \sum_{i=0}^{n} q^{\alpha} \frac{m_{i}}{\ell_{i}} x^{i}$$

where $(m_i, l_i) = 1$, $(m_i,q) = 1$ and $(l_i,q) = 1$, i = 0, ..., n.

From this expression of P(x) we form the ordered pairs (α_i,i) and we plot them on a rectangular coordinate system,

omitting points corresponding to zero coefficients. From these points we construct the Newton Polygon TT which is the convex line enclosing all the points from below. For these polygons Dumas [7] has proved the following

Theorem. The polygon of a product is obtained from the polygons of the factors by joining their sides end to end according to non decreasing slope.

(For the proof of this theorem see [7]).

For example for the prime 3 the factors

$$x^{2} + 3x + 9$$
, $x^{3} - 3x + 27$

have the polygons shown in figures 3 and 4 respectively which are combined in order of increasing slopes to form the polygon shown in figure 5 for the product

 $(x^{2}+3x+9)(x^{3}-3x+27) = x^{5} + 3x^{4} + 6x^{3} + 18x^{2} + 54x + 243$.



powers of X

63



<u>Corollary 5.1</u>. If the polynomial p(x) with rational coefficients is a product of quadratic factors, over the rationals, then its Newton Polygon is combined of sections of (horizontal) length 2. These sections are flat or have $slope \frac{1}{2}$ an integer.

64

§2. Proof of theorem 6

We now apply the method of Newton Polygons to prove theorem 6. We recall that by theorem 4

d = 25 is impossible unless $r > 2s \ge 0$ (case V) d = 24 is impossible unless 2s > r > 0 (case IV) or r = s = 0 (case III)

and we shall prove that even these are impossible.

where r = ord(h) , s = ord(e)
Also p = min(r,2s), u = ord(h-e),
v = ord(h+e), w = ord(e+1)

and

$$L_{d}(Y) = H_{d}(Y) 2^{-p}$$
.

Supposing that our graphs with diameters d = 25 or 24 exist from lemmas 4.4 and 4.5 we have that

$$2u \ge 8 + 2r$$
 when $d = 24$ 5.1

and

$$\min(2r, r+2w) \ge 8 + 2s$$
 when $d = 25$. 5.2

Now for d = 25 or 24 and for Y = z+1 lemma 2.3 gives

$$2^{-p} H_{d}(z) \equiv \begin{cases} (z+1)^{8} \cdot z^{16} & \text{when } r = s = 0 \\ (z+1)^{7} \cdot z^{16} & \text{when } 2s > r > 0 \end{cases} (mod 2)$$

or $r > 2s \ge 0$.

Thus in the polynomial $2^{-p} H_d(z)$, d = 24,25 the coefficient of z^m for any m such that $0 \le m < 16$ is even while the coefficient of z^{16} is odd. Thus for the prime 2 we have





2

S

ŝ

2

2

2

2

2

2

x

×

5

powers

ഗ f 1g .

powers of 2

0

Ξ

2

:

2

c.
<u>Lemma 5.1</u>. If the D-R graphs with diameters d = 25or 24 exist, then the coefficient of z^8 in $2^{-p} H_d(z)$ will be divisible by 2^4 .

<u>Proof.</u> By hypothesis the polynomial $2^{-p} H_d(z)$, d = 25,24is a product of quadratic factors, over the rationals. Thus by corollary 5.1 the non flat section of its Newton Polygon will have slope greater than or equal $\frac{1}{2}$. Therefore the coefficient of z^8 will have order greater than or equal to $\frac{1}{2}$ 8 = 4.

We now prove theorem 6 by showing that there are no D-R graphs with intersection matrix B of diameters d = 25 or 24. <u>Proof.</u> By lemma 5.1 the coefficient of z^8 is divisible by 2^4 . But, by computing coefficients, we get that the actual coefficient is

3.[10505 h² - 407 h(e²+1) - 5716 e²] if d = 25 5.3 3.[5716 h(e²+1) + 4372.e² + 407 (h²-e²)] if d = 24 . 5.4 Now when d = 25 the orders of the terms of the coefficient of z^{8} in $2^{-25} H_{25}(z)$ are

$$2r-2s, r-2s, 2$$
 when $s \neq 0$ 5.5

$$2r$$
, $r+1$, 2 when $s = 0$. 5.6

Let $s \neq 0$. Then w = ord(e+1) = 0 thus from 5.2 we get that $r \geq 8 + 2s$... by 5.5 we get that the coefficient of z^8 in $2^{-2s} H_{25}(z)$ has order 2 which contradicts to lemma 5.1

67

Also when s = 0 since $r \ge 1$ we have that the order of the coefficient of z^8 in $H_{25}(z)$ is again 2.

Next when d = 24 the orders of the terms of the coefficient of z^8 in $2^{-r} H_{24}(z)$ are

2, 2s - r + 2, u + v when 2s > r > 03, 2, u + v when r = s = 0. Now by 5.1 $u \ge 4$ for any $r \ge 0$... u + v > 2. Thus the coefficient of z^8 in $2^{-r} H_{24}(z)$ is not divisible by 2^4 which contradicts to lemma 5.1.

This proves theorem 6.

REFERENCES

- [1] Bannai, E. and T. Ito (1973). On Moore graphs, J. Fac. Sci. Univ. Tokyo Sec. 1A20, 191-208.
- [2] Bannai, E and T. Ito (1977). On the spectra of certain distance-regular graphs, J. Comb. Theory to appear.
- [3] Benson, C.T. (1966). Minimal regular graphs of girth eight and twelve, Canad. J. Math. 18, 1091-1094.
- [4] Berge, C. (1976). Graphs and Hypergraphs, (North-Holland Publishing Company).
- [5] Biggs, N.L. (1974). Algebraic Graph Theory (Cambridge University Press).
- [6] Damerell, R.M. (1973). On Moore graphs, Proc. Cambridge Philos. Soc. 74, 227-236.
- [7] Dumas, M.G. (1906). Sur quelques cas d'irreductibilité de polynomes à coefficients rationnels, Journ. de Math. (6) vol. 2, 191-258.
- [8] Erdelyi, Magnus, Oberhettinger, Tricomi (1953)Higher Transcendental functions. McGraw-Hill.
- [9] Feit, W. and G. Higman (1964). The non-existence of certain generalized polygons, J. Algebra 1, 114-131.
- [10] Hearn, A.C. Reduce 2, A System and Language for Algebraic Manipulation. Proc. of the Second Symposium on Symbolic and Algebraic Manipulation. Los Augeles 1971.
- [11] Hoffman, A.J. (1963). On the polynomial of a graph, Am. Math. Monthly 70, 30-36.

69

- [12] Hoffman, A.J. and R.R. Singleton (1960). On Moore graphs with diameters 2 and 3, IBM J. Res.Dev. 4, 497-507.
- [13] Mowshowitz, A. (1972). The characteristic polynomial of a graph, J. Comb. Theory 12B, 177-193.
- [14] Ore, O. (1922). Zur Theorie dev Irreduzibilitatskriterien, Math. Zeitschrift vol. 20, 278-288.
- [15] Singleton, R.R. (1966) On minimal graphs of maximum even girth, J.Comb. Theory 1, 306-332.
- [16] Tutte, W.T. (1966). Connectivity in graphs. (University Press, Toronto).
- [17] Vijayan, K.S. (1972). Association schemes and Moore graphs, Notices Amer. Math. Soc. 19, A-685.
- [18] Wilson, R.J. (1972). Introduction to graph theory (Oliver and Boyd, Edinburgh).